THE CHARACTERIZATION OF BEST NONLINEAR

TCHEBYCHEFF APPROXIMATIONS

Thesis by

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ABSTRACT

Consider a continuous function, $F(a_1, a_2, \ldots, a_n, x)$ of $n$ parameters and $x \in [0,1]$. Such a function is said to have Property NS if the following theorem is valid for every continuous function, $f(x)$:

**Theorem:** $F(a_1^*, a_2^*, \ldots, a_n^*, x)$ is a best approximation to $f(x)$ if and only if there are $n+1$ distinct points, $0 \leq x_1 < x_2 < \cdots < x_{n+1} \leq 1$, such that $F(a_1^*, a_2^*, \ldots, a_n^*, x_j)$ - $f(x_j)$ = $- [F(a_1^*, a_2^*, \ldots, a_n^*, x_{j+1}) - f(x_{j+1})]$ = $\pm \max_{x \in [0,1]} |F(a_1^*, a_2^*, \ldots, a_n^*, x) - f(x)|$.

Depending on the basic assumptions on $F$, several sets of necessary and sufficient conditions are given for $F$ to have Property NS. These conditions involve unisolventness and related concepts. The definition of Property NS is generalized and necessary and sufficient conditions on $F$ are given for $F$ to have this generalized property. The latter theory includes most common nonlinear approximating functions.
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CHAPTER I

Let two real functions $f$ and $F$ be given such that $f = f(x)$ is a continuous function for $x \in [0,1]$ and $F = F(a^1, a^2, \ldots, a^n, x)$ is a continuous function of $n$ parameters and $x \in [0,1]$. For simplicity of notation the point $(a^1, a^2, \ldots, a^n)$ in Euclidean $n$-space, $\mathbb{E}_n$, is denoted by $a$. The domain of the parameters of $F$ is denoted by $P$, a subset of $\mathbb{E}_n$.

The main problem in the theory of approximation of continuous functions may be stated as follows: Determine $a^* \in P$ so that the deviation of the function $F(a^*, x)$ from $f(x)$ shall be minimized. Naturally one must define the deviation of $F(a^*, x)$ from $f(x)$ and different definitions lead to different theories. In this thesis the deviation of $F(a^*, x)$ from $f(x)$ is taken to be $\max_{x \in [0,1]} |F(a^*, x) - f(x)|$. All maxima and minima are taken over $x \in [0,1]$ unless otherwise stated. $F(a^*, x)$ is said to be a best approximation to $f(x)$ if $\max_{a \in P} |F(a^*, x) - f(x)| \leq \max_{a \in P} |F(a, x) - f(x)|$ for all $a \in P$. The results of this thesis remain valid if $[0,1]$ is replaced by any other closed and bounded interval.

P. L. Tschebycheff [3], [15] was the first to study approximations using this definition of the deviation and the
resulting approximations are called Tchebycheff approximations. Tchebycheff developed his theory extensively for \( F(a,x) = \sum_{k=0}^{n} a^k k^k \) and \( F(a,x) = (\sum_{k=0}^{n} a^k k^k) / (\sum_{k=n+1}^{n+m+2} a^k k^{-n-1}) \) during the period 1855 to 1890. He obtained results for specific examples of \( f(x) \) and he also treated general problems such as the uniqueness and characterization of best approximations. The studies of Tchebycheff were continued in the early part of the 20th century by many mathematicians including S. N. Bernstein, E. Borel, M. Fréchet, A. Haar, P. Kirchberger, Ch. de la Vallée Poussin and L. Tonelli. These mathematicians extended the theory in various directions such as: approximation in two variables [14], approximation in complex variables [10], [14], approximation on a finite point set [11], the existence of best approximations [16], the uniqueness of best approximations [5], [16], approximation by trigonometric functions [9], [4].

By 1920 an elegant theory of Tchebycheff approximation had been developed for \( F(a,x) \) depending linearly on the parameters [2], [12]. Some of the main points of this linear theory are given in the following resume.

Let \( T \) be a set of \( n \) functions \( \phi_1(x), \phi_2(x), \ldots, \phi_n(x) \) continuous on \([0,1] \) and let \( P(a,x) = \sum_{i=1}^{n} a^i \phi_i(x) \) be called a \( T \)-polynomial. \( P(a,x) \) is said to be a non-trivial \( T \)-polynomial if \( \sum_{i=1}^{n} |a^i| > 0 \). \( T \) is said to be a Tchebycheff Set if every
non-trivial polynomial has at most \( n-1 \) zeros. \( \max |F(a,x) - f(x)| \)
is said to alternate \( n \) times if there are \( n+1 \) points
\( 0 \leq x_1 < x_2 < \cdots < x_{n+1} \leq 1 \) such that \( F(a,x_j) - f(x_j) \)
\( = - [F(a,x_{j+1}) - f(x_{j+1})] = \pm \max |F(a,x) - f(x)| \). Alternance is
a basic concept in the theory of Tchebycheff approximations. The
following theorem answers the principal questions of a general
nature in the theory of linear Tchebycheff approximations.

**THEOREM:** Let \( T \) be a Tchebycheff set and let \( f(x) \)
be an arbitrary function continuous on \([0,1]\). Then
A. \( f(x) \) possesses a best approximation,
B. a necessary and sufficient condition that \( F(a_o,x) \)
be a best approximation to \( f(x) \) is that
\( \max |F(a_o,x) - f(x)| \) alternates at least \( n \) times,
C. the best approximation to \( f(x) \) is unique.

It would be desirable to have an explicit method for
determining best approximations, but none exists. Theorem B,
which characterizes best approximations, provides the principal
means of attacking the actual approximation problem [8], [12],
[13].

It is natural to try to extend the theory to cases
where \( F(a,x) \) does not depend linearly on the parameters.
Strangely enough little has been done in this direction except
that the existence of best approximations had been shown for
large classes of non-linear \( F \) and the special case
F(a,x) = \left( \sum_{k=1}^{n} a_k x^k \right) / \left( \sum_{k=n+1}^{n+H+2} a_k x^{k-n-1} \right) 
had been treated by linear techniques.

The first step towards a non-linear theory was made by T. S. Motzkin [7] who introduced the concept of unisolvence. The interpolation problem for a family of functions consists in determining a function of the family which assumes arbitrarily prescribed values at n arbitrarily prescribed distinct values of x ∈ [0,1]. An n-parameter family of functions is said to be unisolvent if the interpolation problem has a unique solution and if the parameters characterizing the solution depend continuously on the points. The definition of unisolvence refers to three independent properties. These are the existence of a solution to the interpolation problem, the uniqueness of this solution and the continuous dependence of the solution on the data. If F is linear and P = E_n then these properties are equivalent. Motzkin noted that if the family of curves defined by F(a,x) were unisolvent then results analogous to A, B, C hold. The only other occurrence of unisolvence in approximation theory is in connection with an algorithm for best approximations [9]. Unisolvence and related concepts will play an important role in this thesis.

The thesis will give some general results on the characterization of best non-linear Tchebycheff approximations. It will go further than to give conditions on F sufficient for the generalization of the classical linear theory to be valid.
Under various basic assumptions on \( F \), it will give criteria which are both necessary and sufficient for the generalization of Theorem B to hold.

A similar problem in the linear theory has been solved by A. Haar [6]. He has shown for \( F(a, x) = \sum_{k=1}^{n} a_k \varphi_k(x) \) that a necessary and sufficient condition on \( F \) for best approximations to be unique is that \( \varphi_1(x), \varphi_2(x), \ldots, \varphi_n(x) \) form a Tchebycheff set. This is to say that a necessary and sufficient condition for Theorem C to be valid is that \( \varphi_1(x), \varphi_2(x), \ldots, \varphi_n(x) \) form a Tchebycheff set.

Let \( Y \) be a set of basic assumptions on \( F \). A natural generalization of Theorem B is: Let \( F \) satisfy \( Y \) and have Property \( X \). Then the alternation of \( \max|F(a^*, x) - f(x)| \) at least \( n \) times is a necessary and sufficient condition for \( F(a^*, x) \) to be a best approximation to \( f(x) \). The problem considered in Chapter II is as follows: given a set \( Y \) determine a Property \( X \) which is both necessary and sufficient for this theorem to hold for all \( f(x) \).

This problem is solved for three sets of basic assumptions on \( F \). The first set essentially assumes only that \( F \) is continuous. The resulting Property \( X \) is quite complicated. The second set assumes that the family of curves defined by \( F \) is closed under pointwise convergence. The resulting Property \( X \) is very closely related to unisolvence. The third set assumes a
stronger closure property for the family of curves defined by $F$. The resulting Property $X$ is unisolvent.

Also given in Chapter II is a theorem from the field of real variables which states: a uniformly bounded infinite set of continuous functions which mutually intersect at most $n$ times contains a pointwise convergent sequence. In Theorems 5 and 6 results are obtained similar to Haar's result with Theorem C replaced by Theorems A and B.

In Chapter III the degree of unisolvent is defined as a function of the parameters. $F$ is said to be unisolvent of degree $k$ at $a^* \in P$ if $F$ is unisolvent for all sets of $k$ points on the graph of $F(a^*,x)$, $x \in [0,1]$. The extension of Theorem B is then taken to be: Let $F$ satisfy $Y$ and have Property $X$. Then a necessary and sufficient condition that $F(a^*,x)$ be a best approximation to $f(x)$ is that $\max|F(a^*,x) - f(x)|$ alternates at least $k$ times. Here $k$ is not assumed to be a constant.

The second set of conditions from Chapter II are taken for $Y$. It is then shown that Property $X$ is "unisolvent of degree $k$ at $a^*$" and is both necessary and sufficient for this theorem to be valid for all $f(x)$. This theory is of great practical interest and includes most common non-linear approximating functions.
CHAPTER II

1. Euclidean n-dimensional space is denoted by $E_n$; points in $E_n$ are denoted by $a, b, \text{ etc.}$ and the coordinates of a are $(a^1, a^2, \ldots, a^n)$. Curly brackets, $\{ \}$, denote a set and $\{ x | \ldots \}$ is read as "the set of $x$ such that $\ldots$". Sequences are denoted by square brackets. All maxima and minima are taken over $x \in [0,1]$ unless otherwise stated.

The real function $F = F(a,x)$ is defined for $x \in [0,1]$ and $a \in P$ where $P$ is a subset of $E_n$. $F$ is continuous in the sense that given $a_0 \in P, x_0 \in [0,1]$ and $\varepsilon > 0$ there is a $\delta > 0$ such that $a \in P, x \in [0,1], |a_0 - a| + |x_0 - x| < \delta$ implies that $|F(a_0, x_0) - F(a, x)| < \varepsilon$. It is assumed that if $a \neq a^*$ then $F(a, x) \neq F(a^*, x)$ for some $x \in [0,1]$. The range of $F$, $R$, is defined to be the set $\{(x, F(a, x)) | x \in [0,1], a \in P\}$ in $x,y$ plane. $f(x), g(x)$, etc. will denote continuous functions on $[0,1]$.

The Tchebycheff Approximation Problem for a continuous function, $f(x)$, may be stated as: Determine $a^* \in P$ such that $\max |F(a^*, x) - f(x)| \leq \max |F(a, x) - f(x)|$ for all $a \in P$. A solution, $F(a^*, x)$, to the approximation problem is called a best approximation to $f(x)$.

The concept of "alternance" plays a major role in the classical theory of Tchebycheff approximation developed for polynomials and Tchebycheff sets. The aim of this chapter is to
study "alternance" in more general situations and to characterize it there. The following definitions are required.

DEFINITION 1: \( \max |F(a^*, x) - f(x)| \) is said to alternate \( k \) times if there are \( k+1 \) points \( 0 \leq x_1 < x_2 < \cdots < x_{k+1} \leq 1 \), such that \( F(a^*, x_j) - f(x_j) = -(F(a^*, x_{j+1}) - f(x_{j+1})) \)

\[ = \pm \max |F(a^*, x) - f(x)|. \] If \( \max |F(a^*, x) - f(x)| \) alternates \( k \) times but not \( k+1 \) times then \( \max |F(a^*, x) - f(x)| \) is said to alternate exactly \( k \) times.

DEFINITION 2: \( F \) has Property N if for every continuous \( f(x) \), the alternance \( n \) times of \( \max |F(a^*, x) - f(x)| \) is a necessary condition for \( F(a^*, x) \) to be a best approximation to \( f(x) \).

DEFINITION 3: \( F \) has Property S if for every continuous \( f(x) \), the alternance \( n \) times of \( \max |F(a^*, x) - f(x)| \) is a sufficient condition for \( F(a^*, x) \) to be a best approximation to \( f(x) \).

DEFINITION 4: \( F \) has Property NS if \( F \) has both Property N and Property S.

From the last definition it is seen that the problem of characterizing "alternance" is the problem of characterizing Property NS.
2. The two properties needed to characterize Property NS are given in Definitions 5 and 6.

**DEFINITION 5:** F has Property Z of degree k if \( a \neq a^* \) implies that \( F(a, x) - F(a^*, x) \) has at most \( k-1 \) zeros in \([0, 1]\).

The phrase "of degree k" is omitted if \( k = n \) is understood.

**DEFINITION 6:** F has Property A if given \( a^* \in P \),

\[
\{ x_j | 0 = x_0 < x_1 < \cdots < x_{k+1} = 1 \} \quad \text{and} \quad \epsilon \text{ with} \quad 0 < \epsilon < \frac{1}{2} \min_j (x_{j+1} - x_j), \ j = 0, 1, \ldots, k \text{ then}
\]

i) there are \( a_1, a_2 \in P \) such that for \( x \in [0, 1] \)

\[
F(a^*, x) - \epsilon < F(a_1, x) < F(a^*, x) < F(a_2, x) < F(a^*, x) + \epsilon
\]

ii) there are \( a_3, a_4 \in P \) such that \( |F(a_3, x) - F(a^*, x)| < \epsilon \), \( |F(a_4, x) - F(a^*, x)| < \epsilon \) for \( x \in [0, 1] \) and

\[
F(a_3, x) - F(a^*, x), F(a_4, x) - F(a^*, x) \text{ change sign from } x_j - \epsilon \text{ to } x_j + \epsilon, \text{ and have no zeros outside } [x_j - \epsilon, x_j + \epsilon], \ j = 1, 2, \ldots, k. \text{ Further } F(a_3, 0) > F(a^*, 0) > F(a_4, 0).
\]

The first theorem characterizing Property NS can now be stated.

**THEOREM 1:** F has Property NS if and only if F has Property A and Property Z.

The proof of Theorem 1 follows from a series of four lemmas.

**LEMA 1:** If F has Property A then F has Property N.
PROOF: Assume that \( F \) has Property A but does not have Property N, i.e., \( F(a^*, x) \) is a best approximation to \( f(x) \) and \( \max |F(a^*, x) - f(x)| \) does not alternate \( n \) times. If \( \max |F(a^*, x) - f(x)| \) does not alternate at all, let \( x_o \) be a point where \( |F(a^*, x) - f(x)| \) assumes its maximum. Say \( F(a^*, x_o) - f(x_o) > 0 \), then by i) of Definition 5 there is an \( a_2 \in \mathcal{P} \) so that \( 0 < F(a^*, x) - F(a_2, x) < \varepsilon \). For \( \varepsilon \) sufficiently small it is seen that \( F(a_2, x) \) is a better approximation to \( f(x) \) than \( F(a^*, x) \). Hence \( \max |F(a^*, x) - f(x)| \) must alternate at least once if \( F \) has Property A.

The interval \([0, 1]\) may be divided into \( \mathcal{P} \) subintervals by \( 0 = x_0 < x_1 < \cdots < x_\mathcal{P} = 1, \mathcal{P} \leq n \) so that i) \( F(a^*, x_j) - f(x_j) = 0, j = 1, 2, \ldots, \mathcal{P} - 1 \) and ii) \( \max |F(a^*, x) - f(x)| \) alternates exactly once on any two adjacent subintervals but does not alternate in any one subinterval. Let \( a_j = \max(F(a^*, x) - f(x)) - \min(F(a^*, x) - f(x)) \) with the maximum and minimum taken over \([x_j, x_{j+1}], j = 0, 1, \ldots, \mathcal{P} - 1\). Let \( \gamma_j = \max |F(a^*, x) - f(x)| \)

\[ -\frac{1}{2} a_j, j = 0, 1, \ldots, \mathcal{P} - 1. \]

About each \( x_j, j = 1, 2, \ldots, \mathcal{P} - 1 \) there is an interval \([x_j - \varepsilon_j, x_j + \varepsilon_j]\) such that in this interval \(|F(a^*, x) - f(x)| \leq \frac{1}{4} \max |F(a^*, x) - f(x)|\). Let \( \varepsilon = \min(\varepsilon_1, \ldots, \varepsilon_{\mathcal{P} - 1}, \gamma_0, \ldots, \gamma_{\mathcal{P} - 1}, \frac{1}{4} \max |F(a^*, x) - f(x)|) \) and determine \( a \in \mathcal{P} \) by ii) of Definition 5 so that \( F(a, x) - F(a^*, x) \) changes sign from \( x_j - \varepsilon \) to \( x_j + \varepsilon, j = 1, 2, \ldots, \mathcal{P} - 1 \) with \( \max |F(a^*, x) - f(x)| < \varepsilon \). Further choose the sign of \( F(a^*, 0) - F(a_0, 0) \) so that

\[ |F(a^*, x) - f(x)| > |F(a, x) - f(x)| \]

in \((0, x_1 - \varepsilon); the same
inequality will then hold outside of \([x_j - \epsilon, x_j + \epsilon], j = 1, 2, \ldots, \ell - 1\).

\(F(a, x)\) is a better approximation to \(f(x)\) than \(F(a^*, x)\) which
contradicts the assumption and proves the lemma.

**LEMMA 2:** If \(F\) has Property \(Z\) then \(F\) has Property \(S\).

**PROOF:** Assume that \(\max |F(a^*, x) - f(x)|\) alternates \(n\) times
and that there is an \(a \in P\) such that \(\max |F(a, x) - f(x)|\)
\(< \max |F(a^*, x) - f(x)|\). Let \(\{x_j | j = 1, 2, \ldots, n+1, x_j < x_{j+1}\}\)
be a set of points in \([0, 1]\) such that \(F(a^*, x_j) - f(x_j)\)
\(= - (F(a^*, x_{j+1}) - f(x_{j+1})) = \pm \max |F(a^*, x) - f(x)|\). Then
\(\text{sgn}(F(a^*, x_j) - F(a, x_j)) = - \text{sgn}(F(a^*, x_{j+1}) - F(a, x_{j+1}))\) which
implies that \(F(a^*, x) - F(a, x)\) has at least \(n\) zeros contradicting
Property \(Z\).

**LEMMA 3:** If \(F\) has Property \(NS\) then \(F\) has Property \(Z\).

**PROOF:** Assume that \(F\) has Property \(NS\) and that there are \(a, a^* \in P\)
such that \(F(a, x) - F(a^*, x)\) has \(n\) or more zeros. Let
\(M(x) = \frac{1}{2} [F(a, x) + F(a^*, x)]; \eta = \frac{1}{2} \max |F(a, x) - F(a^*, x)|\) and let
\(0 \leq x_1 < x_2 < \cdots < x_{n+1} \leq 1\) be \(n\) points where \(F(a, x) - F(a^*, x) = 0\)
along with one point where \(F(a, x) - F(a^*, x) \neq 0\), say \(F(a^*, x_2)\)
\(> F(a, x_2)\) for concreteness. Set \(\delta = \frac{1}{4} \min(x_1, x_2 - x_1, \ldots, x_{n+1} - x_n, 1 - x_{n+1})\) with \(x_1\) or \(1 - x_{n+1}\) omitted if they are zero. A function
\(f(x)\) continuous on \([0, 1]\) will be defined as follows: \(f(x) = M(x)\)
in the intervals \([x_j - \delta, x_{j+1} - \delta], j = 1, 2, \ldots, n;\)
\(f(x) = M(x)\) in \([0, x_1 - \delta]\) if \(x_1 > 0; f(x) = M(x)\) in
[x_{n+1} + \delta, 1] if x_{n+1} < 1; in the remaining intervals f(x) satisfies f(x_j) = F(a^*, x_j) + \frac{(-1)^{j+1}}{2} \frac{\delta}{3} \text{ and } |F(a, x) - f(x)| < \frac{3\delta}{2}, |F(a^*, x) - f(x)| < \frac{3\delta}{2} \text{ for } x \neq x_j.

Now \max|F(a^*, x) - f(x)| \text{ alternates exactly } n \text{ times and } \max|F(a, x) - f(x)| \text{ alternates exactly } n-2 \text{ times. By Property S } F(a^*, x) \text{ is a best approximation to } f(x) \text{ and since } \max|F(a, x) - f(x)| = \max|F(a^*, x) - f(x)| \text{ so } F(a^*, x). \text{ This contradicts Property N and proves the lemma.}

**Lemma 4:** If F has Property NS then F has Property A.

**Proof:** Let a^* \in P, \{x_j|0 = x_0 < x_1 < \cdots < x_{\ell+1} = 1\} \ell \leq n-1 \text{ and } \epsilon \text{ be given with } 0 < \epsilon < \frac{1}{2} \min_{j} (x_{j+1} - x_j),

j = 0, 1, \ldots, \ell. A construction showing the existence of a_3 of Definition 5 will be described, the existence of a_1, a_2 and a_4 follow by similar constructions. A function f(x) will be defined as follows: f(x) is continuous on [0,1]; in [x_j + \epsilon, x_{j+1} - \epsilon], j = 1, 2, \ldots, \ell - 1, f(x) = F(a^*, x) + (-1)^{j+1}(\frac{\epsilon}{3}), and f(x) is linear in each of the remaining intervals. Since \max|F(a^*, x) - f(x)| \text{ alternates at most } \ell \text{ times, } F(a^*, x) \text{ is not a best approximation to } f(x) \text{ by Property N. Hence there is an } a_3 \in P \text{ which is a better approximation to } f(x) \text{ than } F(a^*, x). \text{ This implies that } \max|F(a_3, x) - f(a^*, x)| < \frac{2\epsilon}{3}. \text{ Further } F(a_3, x) - f(a^*, x) \text{ has no zeros outside of the intervals } [x_j - \epsilon, x_j + \epsilon],

j = 1, 2, \ldots, \ell \text{ \ and alternates in sign from } x_j - \epsilon \text{ to } x_j + \epsilon, j = 1, 2, \ldots, \ell.
It is clear that Theorem 1 follows from these four lemmas.

A difficult problem associated with this theorem is the problem of possible improvement. It is difficult to know whether there is some other property, apparently simpler or more restrictive, which, along with Property Z, is equivalent to Property NS. The following example shows that it is unlikely that Theorem 1 can be improved upon in this sense. This example shows that there exists a one parameter function $F$ with Property NS which is unlikely to satisfy any set of conditions simpler than those given for Property A.

Let the number $p$ be of the form $c/2^m$ where $c$ is odd. Then the index $m(p)$ of $p$ is defined to be $m$. The multiplication of a set $P$ of real numbers by a constant $a$ is defined by $aP = \{ap | p \in P\}$ and $p_0 + aP$ means $\{p_0 + ap | p \in P\}$.

Let $P_1 = \{\pm 2^{-j} | j = 1, 2, \ldots \} \cup \{0\}$. $P_k$ is defined recursively from $P_{k-1}$ as follows: let $p \in P_{k-1}$ and form the set $p + P_1/2^{2+m(p)}$, $P_\infty$ is defined to be the union of all such sets for $p \in P_{k-1}$. Let $P = \bigcup_{k=1}^{\infty} P_k$. It may be shown that $P$ is a nowhere dense countable set.

$P$ is taken as the parameter space of $F$ with $F(a,x) = a$ for $a \in P$. Every point of $P$ is the limit from both the left and right of points in $P$, giving $F$ Property A. Hence $F$ so defined has Property A, Property Z and Property NS.
3. With further assumptions on the function $F$ a much simpler and more elegant characterization of Property NS may be given. As a preliminary a theorem in the field of Real Variables is proved, a theorem of some interest in itself.

**THEOREM 2:** Let $\{f_\alpha(x)\}$ be a uniformly bounded infinite set of functions continuous on $[0,1]$ with Property Z. Then $\{f_\alpha(x)\}$ contains a pointwise convergent subsequence.

The proof is broken into four parts. In the following when a sequence of functions is chosen whose function values converge at a particular point, it will always be chosen so that the convergence is monotonic at that point.

**LEMMA 5:** Let $\{f_\alpha(x)\}$ be a uniformly bounded infinite set of functions continuous on $[0,1]$ which are mutually non-intersecting. Then $\{f_\alpha(x)\}$ contains a pointwise convergent sequence.

**PROOF:** Consider $\{f_\alpha(0)\}$ which is a bounded set of real numbers and hence contains a convergent monotonic sequence $[f_\alpha(0)|k = 1, 2, \ldots]$. Since $[f_\alpha(0)]$ is monotonic so is $[f_\alpha(x)]$ monotonic for every $x \in [0,1]$. Since $[f_\alpha(x)]$ is bounded it follows that $[f_\alpha(x)]$ is convergent for every $x \in [0,1]$. 
LEMMA 6: Let \( \{f_{\alpha}(x)\} \) be a uniformly bounded infinite set of functions continuous on \([0,1]\) with Property Z of degree 1. Then \( \{f_{\alpha}(x)\} \) contains a pointwise convergent sequence.

PROOF: For simplicity the sequences \( f_{\mu}(x), f_{2\mu}(x), \ldots \) and \( g_{\mu}(x), g_{2\mu}(x), \ldots \) are denoted by \( F_{\mu} \) and \( G_{\mu} \) and their limits at \( x \) are denoted by \( F_{\mu}(x) \) and \( G_{\mu}(x) \) if these limits exist and if \( F_{\mu}, G_{\mu} \) are monotonic at \( x \). \( F_{\mu} \subset G_{\mu} \) will be used to indicate that \( F_{\mu} \) is a subsequence of \( G_{\mu} \) with the order preserved.

Choose a sequence \( F_{\mu} \) from \( \{f_{\alpha}(x)\} \) such that \( F_{\mu}(0) \) and \( F_{\mu}(1) \) exist. If \( F_{\mu} \) is increasing at both 0 and 1 or decreasing at both points then the functions of \( \{f_{k\mu}(x)\} \) must be mutually non-intersecting and Lemma 5 states that \( F_{\mu} \) is a pointwise convergent sequence.

If \( F_{\mu} \) converges in opposite directions at 0 and 1, then choose \( F_{1} \subset F_{\mu} \) such that \( F_{1}\left(\frac{1}{2}\right) \) exists. The direction of convergence of \( F_{1} \) at \( x = \frac{1}{2} \) must agree with the direction of convergence of \( F_{1} \) at either 0 or 1. Hence a subsequence \( G_{1} \subset F_{1} \) may be chosen which is pointwise convergent in an interval of length \( \frac{1}{2} \) as in Lemma 5.

Choose \( F_{2} \subset G_{1} \) so that \( F_{2} \) converges at the midpoint of the remaining interval. Again the direction of convergence of \( F_{2} \) at the midpoint must agree with the direction of convergence of \( F_{2} \) at one of the endpoints. As in Lemma 5 there is a
subsequence \( G_2 \subseteq F_2 \) which is pointwise convergent except in an interval of length \( \frac{1}{4} \).

In this way an infinite number of subsequences
\[
G_1 \supseteq G_2 \supseteq \cdots \supseteq G_p \supseteq \cdots
\]
may be found where \( G_p \) is pointwise convergent except possibly in an interval of length \( 2^{-p} \). The diagonal sequence of this sequence of sequences may be formed and it converges at all points of \([0,1]\) with possibly one exception. In case the diagonal sequence fails to converge at one point then a further subsequence is chosen that converges there also.

**Lemma 7:** Let \( \{f_\alpha(x)\} \) be a uniformly bounded infinite set of functions continuous on \([0,1]\) with Property Z and such that for every \( x \in [0,1] \), every monotonic infinite sequence from \( \{f_\alpha(x)\} \) is monotonic decreasing. Then \( \{f_\alpha(x)\} \) contains a pointwise convergent sequence.

**Proof:** The proof is by induction on the degree of Property Z. The Lemma has been established for \( n = 0 \) and \( n = 1 \). It will be shown that if the lemma is true for Property Z of degree \( k \) then it is true for Property Z of degree \( k + 2 \).

Select a sequence \( F_0 \) from \( \{f_\alpha(x)\} \) which converges at \( x = 0, \frac{1}{2}, 1 \). \( F_0 \) is monotonically decreasing at these points. The assertion is now made that \( F_0 \) either has a subsequence which is convergent in \([0, \frac{1}{2}]\) or one which is convergent in \([\frac{1}{2}, 1]\).
Assume that there is no convergent subsequence in $\left[\frac{1}{2}, 1\right]$. Then there is an $x_1 \in \left[\frac{1}{2}, 1\right]$ such that $F_o(x_1)$ does not exist. Choose subsequences $F_1 \supseteq F_o$, $G_1 \supseteq F_o$ such that $F_1(x_1) < G_1(x_1)$. For some $k_1$, $f_{k_1}(x_1) < G_1(x_1)$ and therefore there is a subsequence $H_1 \supseteq G_1$ such that every function of $H_1$ intersects $f_{k_1}(x)$ in $\left(\frac{1}{2}, x_1\right)$ and $(x_1, 1)$.

$H_1$ does not converge in $\left[\frac{1}{2}, 1\right]$ and hence there is an $x_2$, say in $\left(x_1, 1\right]$, such that $H_1(x_2)$ does not exist. Choose $F_2 \supseteq H_1$, $G_2 \supseteq H_1$ such that $F_2(x_2) < G_2(x_2)$. Again for some $k_2$, $f_{k_2}(x_2) < G_2(x_2)$ and hence there is a subsequence $H_2 \supseteq G_2$ such that every function of $H_2$ intersects $f_{k_2}(x)$ in $(x_1, x_2)$ and $(x_2, 1)$.

In this way an infinite sequence $F_0^* = \{f_{k_p}(x)\mid =1, 2, \ldots, f_{k_p}(x) \in F_p\}$ is obtained such that every member of this sequence intersects every other member at least twice in $\left[\frac{1}{2}, 1\right]$. Therefore in $\left[0, \frac{1}{2}\right]$, $F_0^*$ has Property Z of degree $k$. The induction hypothesis is applied in $\left[0, \frac{1}{2}\right]$ to obtain a pointwise convergent subsequence $G_0^* \subset F_0^*$.

It has thus been shown that there is a sequence $G_0^*$ from $\{f_o(x)\}$ which converges in an interval of length $\frac{1}{2}$. The entire construction is now repeated to obtain $G_1^* \supseteq G_0^*$ which converges in half of the remaining interval. Continuing in this way a sequence of sequences $G_0^* \supseteq G_1^* \supseteq \cdots$ is obtained which converge except in intervals of length $\frac{1}{2}, \frac{1}{4}, \ldots$. The diagonal process is used as in Lemma 6 to obtain a subsequence which is pointwise convergent in $[0,1]$. 
It is clear that this lemma is also true when decreasing is replaced by increasing.

**PROOF OF THEOREM 2:** The proof is by induction. The induction hypothesis is that the theorem is true for Property 2 of degree \( k \). For \( k = 0 \) the theorem follows from Lemmas 5 and 6.

It is assumed that \( \{ f_\alpha(x) \} \) has Property 2 of degree \( k+1 \). If there is a subset of \( \{ f_\alpha(x) \} \) satisfying the assumptions of Lemma 7 the proof is complete. If there is no such subset then there is a sequence \( F_\circ \) from \( \{ f_\alpha(x) \} \) which has opposite directions of convergence at two points, \( x_1 \) and \( x_2 \). Let \( A \) be the set of points in \([0,1]\) such that all subsequences of \( F_\circ \) are monotonic decreasing or all are monotonic increasing at these points. \( A \) is non-void since it contains \( x_1 \) and \( x_2 \). If \( A \neq [0,1] \) then \( x_3 \) may be chosen in \( A \) and \( x_4 \) not in \( A \) such that \( |x_3 - x_4| \) is arbitrarily small. If \( A = [0,1] \) then \( A \) may be divided into two non-void sets; one with all increasing subsequences and one with all decreasing subsequences. Then \( x_3 \) may be chosen in the first set and \( x_4 \) in the second so that \( |x_3 - x_4| \) is arbitrarily small. In either case there is a subsequence \( F_1 \subset F_\circ \) and \( x_3, x_4 \in [0,1] \) such that \( x_3 < x_4 \), \( F_1 \) has opposite directions of convergence at \( x_3 \) and \( x_4 \) and \( [x_3, x_4] \) has length less than \( \frac{1}{2} \).

Since every member of \( F_1 \) intersects every other member of \( F_1 \) at least once in \([x_3, x_4]\), in each of the intervals \([0, x_3]\) and \([x_4, 1]\) \( F_1 \) has Property 2 of degree \( k \). By the induction hypothesis there is a subsequence \( F_2 \subset F_1 \) which converges point-wise in these intervals.
If \( F_2 \) satisfies the assumptions of Lemma 7 in \([x_3, x_6]\) the proof is complete. If not, a repetition of the above argument shows that there is a subsequence \( F_3 \subset F_2 \) which converges outside of \([x_5, x_6]\) where the length of \([x_5, x_6]\) is less than \( \frac{1}{4} \).

This process is repeated to obtain an infinite number of sequences \( F_1 \supset F_2 \supset \ldots \supset F_\ell \supset \ldots \) where \( F_\ell \) is pointwise convergent except in an interval of length less than \( 2^{-\ell} \). The diagonal sequence may be taken as in Lemma 6 to obtain a pointwise convergent sequence in \([0,1]\).

4. The assumptions on \( F \) with regard to the dependence of \( F(a,x) \) on \( a \) have so far been rather weak. In cases of general interest \( F \) satisfies much more stringent conditions. These conditions are i) a closure property of some kind for the family of functions defined by \( F \) and ii) a regularity property for \( F \). Two such conditions are exactly defined in the following

**DEFINITION 7:** \( F \) is said to be closed if \( F \) is connected and if \( F \) is closed under pointwise limits, i.e.,

\[
\lim_{k \to \infty} F(a_k, x) = G(x) \quad \text{with} \quad (x, G(x)) \in R \quad \text{implies that}
\]

there is an \( a_0 \in P \) such that \( \lim_{k \to \infty} a_k = a_0 \) and hence

\( F(a_0, x) = G(x) \).

The aim of this section is to characterize Property NS with the additional assumption of closure on \( F \).
If $P$ is a connected set then $R$ is seen to be a particularly simple region. Let $L(x) = \{(x,F(a,x))|a \in P\}$. Since $F$ is continuous and $P$ is connected $L(x)$ is a line segment and $R = \bigcup_{x \in [0,1]} L(x)$. Let $L_0(x)$ be the interior of $L(x)$ in the one dimensional topology and let $R_0 = \bigcup_{x \in [0,1]} L_0(x)$.

**Lemma 8:** If $P$ is connected and $F$ has Property NS then given $a^* \in P$ there is an $\epsilon > 0$ such that $(x, F(a^*,x) \pm \epsilon) \in R_0$ for all $x$.

**Proof:** Since $F$ has Property NS, by Theorem 1 $F$ has Property A. By 1) of Property A there are $a_1, a_2 \in P$ such that $F(a_1,x) < F(a^*,x) < F(a_2,x)$. Let $\epsilon_1 = \min|F(a_1,x) - F(a^*,x)|$, $\epsilon_2 = \min|F(a_2,x) - F(a^*,x)|$ and $\epsilon = \frac{1}{2} \min(\epsilon_1, \epsilon_2)$. Since $P$ is connected it is clear that $(x, F(a^*,x) \pm \epsilon) \in R_0$ for all $x$.

The following property will be used in the characterization of Property NS.

**Definition 8:** $F$ is said to be locally solvent if given $0 \leq x_1 < x_2 < \cdots < x_n \leq 1$, $a^* \in P$ and $\epsilon > 0$ there is a $\delta(a^*, \epsilon, x_1, x_2, \ldots, x_n) > 0$ such that $|y_j - F(a^*,x_j)| < \delta$ implies the existence of a solution $a \in P$ to $F(a,x_j) = y_j$ with $\max|F(a,x) - F(a^*,x)| < \epsilon$.

**Definition 9:** $F$ is said to be locally unisolvient if $F$ is locally solvent and has Property Z.
LEMMA 9: If $P$ is connected and $F$ is locally unisolvent then $R = R_0$.

PROOF: Assume that $(x_o, y_o) \not\in R_0$ with $y_o = F(s^*, x_o)$. By the local solvence of $F$ there is a $\delta_o(s^*, x_o, \ldots) > 0$ and $a_1, a_2 \in P$ such that $F(a_1, x_o) = F(s^*, x_o) + \frac{1}{2} \delta_o$, $F(a_2, x_o) = F(s^*, x_o) - \frac{1}{2} \delta_o$. This is a contradiction and proves the lemma.

The purpose of Lemma 9 is to show that Property NS and local unisolvence each imply that $R = R_0$ if $P$ is connected.

A zero $x_o$ of $f(x)$ is said to be a simple zero if $f(x)$ changes sign at $x_o$ and a double zero if $f(x)$ does not change sign at $x_o$. The following lemma shows that if $F$ is locally unisolvent then Property Z is valid counting the multiplicity of zeros.

LEMMA 10: Let $F$ be locally unisolvent. Then $F(a, x) - F(a^*, x)$ cannot have more than $n-1$ zeros counting multiplicities.

PROOF: Let $\{x_j | j = 1, 2, \ldots, k\}$ be the set of zeros of $F(a, x) - F(a^*, x)$. Assume, for concreteness, that $x_1$ is a double zero and $F(a, x) - F(a^*, x) > 0$ near $x_1$. Since $F$ is locally solvent there is an $a_1 \in P$ such that $F(a_1, x_j) = F(a, x_j)$ for $j \neq 1$, $F(a_1, x_1) < F(a, x_1)$ and $\max|F(a_1, x) - f(a, x)| < \epsilon$. For $\epsilon$ sufficiently small it is clear that 1) $\{x_j | j = 2, 3, \ldots, k\}$ are zeros of $F(a, x) - F(a^*, x)$; ii) every double zero of $F(a, x) - F(a^*, x)$ is either a double zero of $F(a_1, x) - F(a^*, x)$
or has been replaced by two simple zeros. iii) \( F(a_1, x) - F(a^*, x) \) has two simple zeros near \( x_1 \). Hence, counting multiplicities, the number of zeros of \( F(a_1, x) - F(a^*, x) \) is the same as the number of zeros of \( F(a, x) - F(a^*, x) \). This process is continued to obtain \( a_m \in \mathbb{P} \) such that \( F(a_m, x) - F(a^*, x) \) has all simple zeros and the number of zeros of \( F(a_m, x) - F(a^*, x) \) and \( F(a, x) - F(a^*, x) \) is the same counting multiplicities. This completes the proof.

Property NS can now be characterized by

**THEOREM 3:** If \( F \) is closed then local unisolvence is a necessary and sufficient condition for \( F \) to have Property NS.

The fact that \( F \) is closed leads to the following stronger form of Lemma 4.

**LEMMA 11:** Let \( F \) be closed and have Property NS. Then given \( a^* \in \mathbb{P}, \varepsilon > 0 \) and a set \( \{x_j | 0 = x_0 \leq x_1 < \cdots < x_k \leq x_{k+1} = 1; k < n \} \) there are \( a_1, a_2 \in \mathbb{P} \) so that

i) \( F(a_1, x) - F(a^*, x), F(a^*, x) - F(a_2, x) \) change sign at the \( x_j, j = 1, 2, \ldots, k \) and at no other points.

ii) \( |F(a_1, x) - F(a^*, x)| \leq \varepsilon, |F(a_2, x) - F(a^*, x)| \leq \varepsilon \)

iii) either \( F(a_1, x) - F(a^*, x) = 0, F(a_2, x) - F(a^*, x) = 0 \) or \( \text{sgn}[F(a_1, x) - F(a^*, x)] = -\text{sgn}[F(a_2, x) - F(a^*, x)] \).

**PROOF:** The proof is given for \( a_2 \), the proof for \( a_1 \) follows in the same way. By Lemma 8 it is possible to take \( \varepsilon \) small enough that \( (x, F(a^*, x) \pm \varepsilon) \in \mathbb{R}_0^+ \) for all \( x \). Let

\[
\frac{1}{f_0} < \frac{1}{4} \min(x_1, x_2 - x_1, \ldots, x_k - x_{k-1}, 1 - x_k) \text{ where } x_1
\]
or 1 - \( x_k \) is omitted if they are zero. A sequence of functions
\[
[f_\lambda(x)] \forall \lambda = f_\lambda, f_{\lambda + 1}, \ldots
\]
will be defined so that \( f_\lambda(x) \) is continuous in \([0, 1]\), in the intervals \([x_j + \frac{1}{n}, x_{j+1} - \frac{1}{n}]\),
\( j = 2, 3, \ldots, k-1 \), \( f_\lambda(x) = P(a^*_k, x) + (-1)^j \frac{\xi}{3} \) if \( x_j > 0 \)
\( f_\lambda(x) = P(a^*_k, x) + \frac{\xi}{3} \) in \([0, x_j - \frac{1}{n}]\); if \( x_j < 1 \),
\( f_\lambda(x) = P(a^*_k, x) + (-1)^k \frac{\xi}{3} \) in \([x_k, 1] \); \( f_\lambda(x) \) is linear in each of
the remaining intervals. \( P(a^*_k, x) \) is not a best approximation
to any \( f_\lambda(x) \) for \( \max|P(a^*_k, x) - f_\lambda(x)| \) alternates at most \( k \) times.
However it will be shown that there is a \( b_\lambda \in P \) such that
\( F(b_\lambda, x) \) is a best approximation to \( f_\lambda(x) \).

Consider a sequence \([F(b_{\lambda_i}, x)] \forall i = 1, 2, \ldots\) for which
\[
\lim_{i \to \infty} \max_{a \in P} |F(b_{\lambda_i}, x) - f_\lambda(x)| = \inf_{a \in P} \max_{F(a, x) - f_\lambda(x)} \{F(b_{\lambda_i}, x)\}
\]
forms a bounded infinite set of continuous functions. This set has
Property Z by Lemma 3. Theorem 2 may be applied to extract a
convergent subsequence of \([F(b_{\lambda_i}, x)]\). By the closure of \( F \) the
subsequence has a limit, \( F(b_\lambda, x) \), which is a best approximation
to \( f_\lambda(x) \).

In the same way \([F(b_\lambda, x)] \forall \lambda = f_\lambda, f_{\lambda + 1}, \ldots\) has a
limit \( F(a_2, x) \). Clearly \( 0 \leq [F(a_2, x) - F(a^*_k, x)] (-1)^j \leq (-1)^j \epsilon \)
in \( (x_j, x_{j+1}) \), \( j = 0, 1, 2, \ldots, k \). If \( a_2 \neq a^*_k \) then it is seen
that \( F(a_2, x) - F(a^*_k, x) \) changes sign at the \( x_j, j = 1, 2, \ldots, k \)
and nowhere else.

It remains to be shown that \( a_2 \neq a^*_k \). Since
\( \max|F(b_\lambda, x) - f_\lambda(x)| \) alternates \( n \) times, \( \max|F(b_\lambda, x) - F(a^*_k, x)| > \frac{\xi}{3} \).
By the closure of \( F \lim_{\mathcal{F}} b_F = a_2 \). Since
\[
\max |F(a, x) - F(a^*, x)|
\]
is a continuous function of \( a \) it follows that
\[
\lim_{\mathcal{F} \to \infty} \max |F(b_F, x) - F(a^*, x)| \geq \frac{\delta}{3} \quad \text{and} \quad a_2 \neq a^*.
\]

**DEFINITION 10:** \( F(a, x) \) is said to be between \( F(a_1, x) \) and \( F(a_2, x) \) if
\[
|F(a_1, x) - F(a, x)| + |F(a, x) - F(a_2, x)| = |F(a_1, x) - F(a_2, x)| \quad \text{for all} \quad x \in [0, 1].
\]

**LEMMA 12:** Let \( F(a_1, x) - F(a_2, x) \) change sign at \( n-1 \) distinct points and let \( F(a_1, x_0) \neq F(a_2, x_0) \). If \( F \) is closed and has Property NS then given \( y \) between \( F(a_1, x_0) \) and \( F(a_2, x_0) \) there is an \( a \in F \) such that \( F(a, x_0) = y \) and \( F(a, x) \) is between \( F(a_1, x) \) and \( F(a_2, x) \).

**PROOF:** Since \( F \) has Property NS it follows from Lemma 3 that \( F \) has Property Z and hence \( F(a_1, x) - F(a_2, x) \) has exactly \( n-1 \) zeros.

For concreteness assume \( F(a_1, x_0) > F(a_2, x_0) \) and let
\[
I = [F(a_2, x_0), F(a_1, x_0)] \quad \text{and} \quad A \quad \text{be the subset of} \quad I \quad \text{for which the lemma is true.}
\]

It will now be shown that \( A \) is a closed set. Let
\[
[y_j | j = 1, 2, \ldots, y_j \in A] \quad \text{be given with} \quad \lim_{j \to \infty} y_j = y_0.
\]
Corresponding to \([y_j]\) there is a sequence \([F(a_j, x)|F(a_j, x_0) = y_j]\) of functions between \( F(a_1, x) \) and \( F(a_2, x) \). Theorem 2 is applicable to this sequence and hence \([F(a_j, x)]\) has a pointwise convergent subsequence. Since \( F \) is closed this subsequence has a limit \( F(a_0, x) \) and \( F(a_0, x_0) = y_0 \) which implies \( y_0 \in A \).
It will now be shown that \( I - A \) is empty. \( I - A \) is an open set. If \( I - A \) is not empty it contains an open interval \((y_0, y_1)\) with \( y_0, y_1 \in A \). Since \( y_0 \in A \) there is an \( a_3 \in P \) so that \( F(a_3, x_0) = y_0 \) and \( F(a_3, x) \) is between \( F(a_1, x) \) and \( F(a_2, x) \). By Lemma 11 there is an \( a_4 \in P \) such that \( F(a_4, x) \) is between \( F(a_1, x) \) and \( F(a_2, x) \) and \( y_0 < F(a_4, x_0) < y_1 \). This contradicts the existence of an open interval in \( I - A \) and \( A = I \).

**Lemma 13:** If \( F \) is closed and has Property NS then \( F \) is locally solvent.

**Proof:** The proof is conducted by an induction argument. The statement to be verified by induction is: Let \( a^* \in P, \varepsilon > 0 \) and a set \( \{x_j | 0 \leq x_1 < x_2 < \cdots < x_n \leq 1\} \) be given. Then there is a \( \delta(a^*, \varepsilon, k, x_j) > 0 \) such that \( |y_j - F(a^*, x_j)| \leq \delta \) for \( j = 1, 2, \ldots, k \) implies that there is an \( a \in P \) such that \( F(a, x_j) = y_j \), \( j = 1, 2, \ldots, k \); \( |F(a, x) - F(a^*, x)| < \varepsilon \) and \( F(a, x_j) = F(a^*, x_j) \), \( j = k+1, \ldots, n \). The induction is on \( k \) and for \( k = n \) the statement implies that \( F \) is locally solvent.

For \( k = 1 \) this statement will be established from Lemmas 11 and 12. Let \( F(a_1, x) \) and \( F(a_2, x) \) be determined by Lemma 11 so that \( F(a_1, x_j) = F(a_2, x_j) = F(a^*, x_j) \), \( j = 2, 3, \ldots, n \); \( |F(a_1, x) - F(a^*, x)| < \varepsilon \), \( |F(a_2, x) - F(a^*, x)| < \varepsilon \) and \( F(a_1, x_1) > F(a^*, x_1) > F(a_2, x_1) \). Since \( F(a_1, x), F(a_2, x) \) intersect at \( n-1 \) points it is not possible that \( F(a_1, x_1) = F(a^*, x_1) \) or
$F(a_2, x_1) = F(a^*, x_1)$. Take $\delta(a^*, \epsilon, 1, x_j) = \min(|F(a_1, x_1) - F(a^*, x_1)|, |F(a_2, x_1) - F(a^*, x_1)|)$ and the statement follows for $k = 1$ by Lemma 12.

In order to proceed with the general induction step some auxiliary facts will be established. Let $\vec{y} = (y^1, y^2, \ldots, y^k)$ be a point in $E_k$ and let $A = \left\{ y^i \mid y^i = F(a^*, x_1) \leq \delta(a^*, \epsilon, k, x_j), i = 1, 2, \ldots, k \right\}$. Define two subsets, $P_1(\vec{y})$ and $P_2(\vec{y})$, of $P$ as follows: $|F(a, x) - F(a^*, x)| < \epsilon$ for $a \in P_1(\vec{y})$, $a \in P_2(\vec{y})$; $F(a, x_j) = y^j$, $j = 1, 2, \ldots, k$, $a \in P_1(\vec{y})$, $a \in P_2(\vec{y})$; $F(a, x_j) = F(a^*, x_j)$, $j = k+2, \ldots, n$, $a \in P_1(\vec{y})$, $a \in P_2(\vec{y})$; $F(a, x_{k+1}) > F(a^*, x_{k+1})$, $a \in P_1(\vec{y})$; $F(a, x_{k+1}) < F(a^*, x_{k+1})$, $a \in P_2(\vec{y})$.

Let $\delta_1(\vec{y}) = \sup_{a \in P_1(\vec{y})} (F(a, x_{k+1}) - F(a^*, x_{k+1})), \delta_2(\vec{y}) = \sup_{a \in P_2(\vec{y})} (F(a^*, x_{k+1}) - F(a, x_{k+1}))$. It follows from Lemma 11 that $P_1(\vec{y})$ and $P_2(\vec{y})$ are non-empty and that $\delta_1(\vec{y}) > 0, \delta_2(\vec{y}) > 0$. 

\[
\begin{aligned}
 & (x_{k-1}, y^{k-1}) & & (x_k, y^k) \\
 & (x_j, y^j) & & (x_{k+1}, y_{k+1}) \\
 \end{aligned}
\]
It will now be shown that for any \( \bar{y}_o \in A \) there is a neighborhood, \( N(\bar{y}_o) \), of \( \bar{y}_o \) such that \( \bar{y} \in N(\bar{y}_o) \) implies \( \delta_1(\bar{y}) \geq \frac{1}{2} \delta_1(\bar{y}_o) \). There is an \( a_1 \in P_1(\bar{y}_o) \) such that
\[ F(a_1, x_{k+1}) \geq F(a^*, x_{k+1}) + \frac{1}{2} \delta_1(\bar{y}_o). \]
Hence by the induction statement applied to \( F(a_1, x) \) there is a \( \delta_2(a_1, \gamma, k, x_j) > 0 \) such that for every \( \bar{y} \) with \( |y^j - y_o^j| < \delta_2 \) there is an \( F(a, x) \) so that i) \( F(a_j, x_j) = y^j, j = 1, 2, \ldots, k \) ii) \( F(a, x_j) = F(a_1, x_j) = F(a^*, x_j), j = k+2, \ldots, n \), iii) \( F(a, x_{k+1}) = F(a_1, x_{k+1}) \geq F(a^*, x_{k+1}) + \frac{1}{2} \delta_1(\bar{y}_o) \). Further \( |F(a, x) - F(a_1, x)| < \gamma \) and for \( \gamma \) sufficiently small \( |F(a, x) - F(a^*, x)| < \varepsilon \). Hence \( \delta_2 \) defines a neighborhood, \( N(\bar{y}_o) \) so that for every point \( \bar{y} \) of \( N(\bar{y}_o) \) there is an \( a \in A_1(\bar{y}) \) with \( F(a, x_{k+1}) \geq F(a^*, x_{k+1}) + \frac{1}{2} \delta_1(\bar{y}_o) \).

It will now be shown that \( \delta_1(\bar{y}) \) is bounded away from zero for \( \bar{y} \in A \). A is a compact set which has an open covering by neighborhoods, \( \left\{ N(\bar{y}) \mid \bar{y} \in A \right\} \). Hence \( A \) has a finite covering \( N(\bar{y}_1), \ldots, N(\bar{y}_m) \) and \( \delta_1(\bar{y}) \geq \frac{1}{2} \min [\delta_1(\bar{y}_1), \delta_1(\bar{y}_2), \ldots, \delta_1(\bar{y}_m)] \) = \( \delta_1 > 0 \). A similar argument shows that \( \delta_2(\bar{y}) \geq \delta_2 > 0 \).

The general induction step can now be made with the preceding construction and Lemma 12. For \( k > 1 \) take
\[ \delta(a^*, \varepsilon, k+1, x_j) = \min \left[ \frac{1}{2} \delta_1, \frac{1}{2} \delta_2, \delta(a^*, \varepsilon, k, x_j) \right]. \]
Given any set \( \{ y^j \mid j = 1, 2, \ldots, k+1, |F(a^*, x_j) - y^j| \leq \delta(a^*, \varepsilon, k+1, x_j) \} \) then there are \( a_1, a_2 \in P \) such that i) \( F(a_1, x_j) = F(a_2, x_j) = y^j \), \( j = 1, 2, \ldots, k \), ii) \( F(a_1, x_{k+1}) \geq F(a^*, x_{k+1}) + \delta(a^*, \varepsilon, k+1, x_j) \),
\[ F(a_2', x_{k+1}') \leq F(a^*, x_{k+1}) - \delta (a^*, \epsilon, k+1, x_j); \ iii) F(a_1, x_j) = F(a_2, x_j) = F(a^*, x_j), \ j = k+2, \ldots, n; \ iv) |F(a_1, x) - F(a^*, x)| < \epsilon, \ |F(a_2, x) - F(a^*, x)| < \epsilon. \] By Lemma 12 there is an \( a_3 \in P \) such that \( F(a_3, x_{k+1}) = y^{k+1} \) and \( F(a_3, x) \) is between \( F(a_1, x) \) and \( F(a_2, x) \). This concludes the induction step and it follows from the induction statement for \( k = n \) that \( F \) is locally solvent.

**Lemma 14:** If \( F \) is closed and locally unisolvent then \( F \) has Property N.

**Proof:** Assume that \( \max |F(a^*, x) - f(x)| \) alternates exactly \( k \) times, \( k < n \). It will be shown that \( F(a^*, x) \) cannot be a best approximation to \( f(x) \).

If \( \max |F(a^*, x) - f(x)| \) is not assumed at both 0 and 1 then one of the intervals \( [0, \delta], [1-\delta, 1] \), say \( [0, \delta] \) for concreteness, is chosen with \( \delta \) determined so that for \( x \in [0, \delta] \) and some \( \epsilon_0 > 0 \), we have \( |F(a^*, x) - f(x)| < \max |F(a^*, x) - f(x)| - \epsilon_0 \). Let \( 0 = x_0 < x_{n-k} < x_{n-k+1} < \cdots < x_n = 1 \) divide \( [0, 1] \) into \( k+1 \) subintervals so that i) \( F(a^*, x_j) - f(x_j) = 0, j = n-k, n-k+1, \ldots, n-1; \) ii) \( \max |F(a^*, x) - f(x)| \) alternates exactly once in any two adjacent subintervals but does not alternate in any one subinterval. Choose \( n-k-1 \) distinct points, \( \{x_j | j = 1, 2, \ldots, n-k-1, x_j < x_{j+1}\} \), in \( [0, \delta] \). Let \( \alpha_j = \max(F(a^*, x) - f(x)) - \min(F(a^*, x) - f(x)) \) with the maximum and minimum taken over \( [x_j, x_{j+1}] \), \( j = n-k-1, n-k, \ldots, n-1 \). Let \( \gamma_j = \max |F(a^*, x) - f(x)| - \frac{1}{2} \alpha_j, j = n-k-1, n-k, \ldots, n-1 \) and \( \epsilon = \min(\gamma_{n-k-1}, \ldots, \gamma_{n-1}, \frac{1}{2} \epsilon_0) \). Let \( x' \) denote a point where \( \max |F(a^*, x) - f(x)| \) is attained.
Since \( F \) is locally solvent there is an \( a \in P \) such that 
\[
F(a,x) - F(a^*,x) \text{ changes sign at } x_j, \ j = 1, 2, \ldots, n-1 \text{ and }
\]
\[
|F(a,x') - f(x')| < |F(a^*,x') - f(x')| \quad \text{with } \max |F(a,x) - F(a^*,x)| < \epsilon.
\]
Since \( F(a,x) - F(a^*,x) \) cannot have any more zeros \( F(a,x) \) is uniformly closer to \( f(x) \) than \( F(a^*,x) \) except in \( [0, \delta] \). Therefore \( F(a,x) \) is a better approximation than \( F(a^*,x) \) to \( f(x) \).

If \( \max |F(a^*,x) - f(x)| \) is assumed at both 0 and 1 let the interval \( [0, \delta] \) be replaced by \( [x_{n-k-\delta}, x_{n-k}] \) where 
\[
\{x_j| j = 0, n-k, \ldots, n\}, \delta, \epsilon_0, \alpha_j, \eta_j \text{ and } \epsilon \text{ are defined in a manner analogous to the preceding construction. For } n-k-1 \text{ even choose } n-k-1 \text{ points } \{x_j|x_{n-k-\delta} \leq x_1 < x_2 < \cdots < x_{n-k-1} < x_{n-k}\}
\]
and determine \( a \in P \) so that 
\[
|F(a,0) - f(0)| < |F(a^*,0) - f(0)|, 
|F(a,1) - f(1)| < |F(a^*,1) - f(1)|, |F(a,x) - F(a^*,x)| < \epsilon \text{ and } 
F(a,x) - F(a^*,x) \text{ changes sign at the } x_j, \ j = 1, 2, \ldots, n-1. 
F(a,x) \text{ is a better approximation than } F(a^*,x) \text{ to } f(x). \] 
For \( n-k-2 \) even choose \( n-k-2 \) points 
\[
\{x_j|x_{n-k-\delta} \leq x_1 < x_2 < \cdots < x_{n-k-1} < x_{n-k}\}
\]
and determine \( a \) so that 
\[
|F(a,0) - f(0)| < |F(a^*,0) - f(0)|, 
|F(a,1) - f(1)| < |F(a^*,1) - f(1)|, |F(a,x) - F(a^*,x)| < \epsilon \text{ for } 
x \in [0,1] \text{ and } F(a,x) - F(a^*,x) \text{ changes sign at the } x_j, 
j = 2, 3, \ldots, n-1. \ F(a,x) - F(a^*,x) \text{ cannot have another zero without having two more, counting multiplicity, and hence } F(a,x) \text{ is a better approximation than } F(a^*,x) \text{ to } f(x). \] 
This concludes the proof.

PROOF OF THEOREM 3: The statement of Theorem 3 may be considered as a set of four statements, namely Lemmas 2, 3, 13 and 14, all of which have been established as true.
5. In Theorem 3 Property NS is characterized by mainly local properties of the function $F$. If a stronger closure condition is imposed on $F$ then Property NS can be characterized by "global" properties of $F$. This stronger condition is satisfied by the common forms of $F$.

**DEFINITION 11:** $F$ is said to be solvent if $F$ is locally solvent and if given a set $\{(x_j, y_j) | 0 \leq x_1 < x_2 < \cdots < x_n \leq 1, (x_j, y_j) \in \mathbb{R}\}$ then there is a solution, $a \in \mathbb{F}$, to the equations $F(a, x_j) = y_j$, $j = 1, 2, \ldots, n$.

**DEFINITION 12:** $F$ is said to be unisolvent if $F$ is solvent and has Property Z.

**DEFINITION 13:** $F$ is n-point closed if $F$ is connected and if $F$ is closed under pointwise convergence at any $n$ points, i.e., $\lim_{k \to \infty} F(a_k, x_j) = y_j$, $j = 1, 2, \ldots, n$ with $(x_j, y_j) \in \mathbb{R}$ implies the existence of an $a_0 \in \mathbb{F}$ such that $F(a_0, x_j) = y_j$. It is seen that if $F$ is n-point closed then $F$ is closed.

**THEOREM 4:** If $F$ is n-point closed then unisolvence is a necessary and sufficient condition for $F$ to have Property NS.

Lemmas 2, 3 and 14 still apply here as in the proof of Theorem 3 and only Lemma 13 needs to be replaced.

**LEMMA 15:** If $F$ is n-point closed and has Property NS then $F$ is solvent.
Let \( \{x_j \mid x_j \in [0,1], \ j = 1, 2, \ldots, n \} \) be an arbitrary set of \( n \) points which shall remain fixed through the first portion of this proof. Relative to this set define \( U = \{y \mid y \in E_n, \ y^j = F(a, x_j), \ a \in \mathbb{P} \} \). Recall the definition of \( L_\mathbb{E}(x) \) in the discussion preceding Lemma 8. Let \( L_\mathbb{E}(x) \) be the closed interval obtained by shortening \( L_\mathbb{E}(x) \) by \( \varepsilon \) at each end. Let \( W_\varepsilon = \{y \mid y \in E_n, \ y^j \in L_\varepsilon(x_j) \} \). \( W_\varepsilon \) is seen to be an \( n \)-dimensional parallelepiped. It will be shown that \( \bigcap W_\varepsilon = W_\varepsilon \) for all \( \varepsilon \) sufficiently small.

It follows from the \( n \)-point closure of \( F \) that \( \bigcap W_\varepsilon \) is a closed set in \( E_n \).

Since \( n \)-point closure implies closure it follows from Theorem 3 that \( F \) is locally unisolvent. Let \( y_\circ \) be any point of \( W_\varepsilon \). Since \( F \) is locally solvent it follows that there is a \( \delta(y_\circ, x_j) > 0 \) defining an \( n \)-dimensional cube about \( y_\circ \) which is in \( U \). Hence \( W_\varepsilon \cap U \) is an open set relative to \( W_\varepsilon \).

Since \( R = R_\circ \) is non-empty it is clear that for some \( \varepsilon_\circ > 0 \), \( W_{\varepsilon_\circ} \cap U \) is non-empty. Therefore \( W_{\varepsilon_\circ} \cap U \) is a non-empty set which is both open and closed relative to \( W_{\varepsilon_\circ} \) and \( W_{\varepsilon_\circ} \cap U = W_{\varepsilon_\circ} \). It is clear that for \( \varepsilon < \varepsilon_\circ \), \( W_\varepsilon \cap U \) is non-empty and hence \( W_\varepsilon \cap U = W_\varepsilon \) for \( \varepsilon \leq \varepsilon_\circ \).

Since \( R = R_\circ \), any set \( \{y^j \mid y^j \in L_\mathbb{E}(x_j), \ j = 1, 2, \ldots, n \} \) is represented by a point in \( W_\varepsilon \) for some \( \varepsilon \leq \varepsilon_\circ \). Therefore there is an \( a \in \mathbb{P} \) so that \( F(a, x_j) = y^j, \ j = 1, 2, \ldots, n \), for any set \( \{y^j \mid (x_j, y^j) \in R, \ j = 1, 2, \ldots, n \} \).
6. It has been seen that the nature of \( P \) plays an important role in this theory. In the classical theory for Tchebysheff sets it is always assumed that \( P = E_n \). From the example following Theorem 1 it is seen that \( P \) need not be \( E_n \) in order for a linear approximating function to have Property NS. The question then naturally arises: can Theorems A and B of the introduction be true for a linear approximating function with \( P \neq E_n \)? It has been shown [6] that Property Z is a necessary and sufficient condition for Theorem C to be valid. Theorem 5 gives conditions on \( P \) and \( F \) in order that either Theorem A or Theorem B be valid for a linear approximating function. The question raised above is answered negatively by Theorem 6.

**THEOREM 5:** Let \( F(a,x) = \sum_{j=1}^{n} a_i \phi_j(x) \) where \( \phi_j(x) \) is continuous on \([0,1]\). If \( \det(\phi_j(x_j)) \neq 0 \) for each set \( \{x_j| j = 1, 2, \ldots, n, x_j < x_{j+1}, x_j \in [0,1]\} \) then

i) \( F \) has Property NS if and only if \( P \) is open,

ii) Every continuous function has a best approximation if and only if \( P \) is closed.

**PROOF:** Since the proof of this theorem is straightforward but involved only a sketch of the proof is given.

1) If \( P \) is open then clearly \( F \) is locally solvent and hence has Property NS.

Assume \( F \) has Property NS and that \( P \) contains one of its boundary points, \( a_0 \). Let \( \{x_j| j = 1, 2, \ldots, n, x_j \in [0,1]\} \) be a set of \( n \) distinct points. Consider the mapping, \( T \), from \( E_1 \)
onto $E_n$ defined by

$$T(a^1, a^2, \ldots, a^n) = \left( \sum_{i=1}^{n} a^i \varphi_i(x_i) \right),$$

$$\sum_{i=1}^{n} a^i \varphi_i(x_1), \ldots, \sum_{i=1}^{n} a^i \varphi_i(x_n).$$

Since $\det(\varphi_i(x_j)) \neq 0$, $T$ is a one-to-one continuous mapping. Any neighborhood of $T(a^1_0, a^2_0, \ldots, a^n_0)$ contains points which are not the image under $T$ of points of $P$. Therefore $F$ cannot be locally solvent near $F(a_0, x)$.

ii) Let $\rho = \inf_{a \in P} \max_{x} |F(a, x) - f(x)|$ then it can be shown, [1]

page 10, that there is an $M < \infty$ such that $\sum_{i=1}^{n} |a^i| > M$ implies

$\max_{a \in P} |F(a, x) - f(x)| > \rho + 1$. $f(x)$ has a best approximation if there is an $a^* \in P$ such that $\max_{a \in P} |F(a^*, x) - f(x)| = \inf_{a \in P} \max_{x} |F(a, x) - f(x)|$.

Let $P_M = \left \{ a^i \in P, \sum_{i=1}^{n} |a^i| \leq M \right \}$. Clearly a may be restricted to values from $P_M$. If $P$ is closed then

$\inf_{a \in P_M} \max_{x} |F(a, x) - f(x)|$

is attained and $f(x)$ possesses a best approximation.

Assume $P$ is not closed and that $P \neq E_n$. Let $a_0$ be a boundary point of $P$ not contained in $P$. A function $f(x)$ is defined so that $\max_{a \in P} \left| \sum_{i=1}^{n} a^i_0 \varphi_i(x) - f(x) \right|$ alternates $n$ times. Then clearly

$\inf_{a \in P} \max_{x} |F(a, x) - f(x)| \leq \max_{a \in P} \left| \sum_{i=1}^{n} a^i_0 \varphi_i(x) - f(x) \right|$. If $f(x)$ possesses a best approximation, \( \sum_{i=1}^{n} a^i_0 \varphi_i(x) \), then

$\sum_{i=1}^{n} (a^i_0 - a^i) \varphi_i(x)$

has at least $n$ zeros which contradicts $\det(\varphi_i(x_j)) \neq 0$. This completes the sketch.

**THEOREM 6:** Let $F(a, x) = \sum_{i=1}^{n} a^i \varphi_i(x)$ where $\varphi_i(x)$ is continuous on $[0, 1]$. Theorems A and B are both valid for $F$ if and only if \( \left\{ \varphi_i(x) | i = 1, 2, \ldots, n \right\} \) is a Tchebycheff set and $P = E_n$. 
PROOF: It is a classical result that Theorems A and B are valid if \( \{ \varphi_i(x) \} \) is a Tchebycheff set and \( P = E_n \).

It will be shown that i) if \( \det(\varphi_i(x_j)) = 0 \) for some set \( \{ x_j \} \) of distinct points and \( P = E_n \) then Theorem B is not valid. ii) if \( \det(\varphi_i(x_j)) = 0 \), \( P \neq E_n \) and Theorems A and B are valid then \( P \) is the empty set. It follows directly from Theorem 5 that if \( \det(\varphi_i(x_j)) \neq 0 \) for all \( \{ x_j \} \) then the validity of Theorems A and B imply \( P = E_n \).

i) Since \( P = E_n \) and \( \det(\varphi_i(x_j)) = 0 \) there is a non-trivial T-polynomial with \( n \) zeroes. This contradicts Property Z and hence Theorem B.

ii) The same proof as in Theorem 5 applies to show that \( P \) is both open and closed. Hence \( P \) is the empty set. This concludes the proof.
CHAPTER III

1. Often when one is using common non-linear approximating functions it develops that Property NS is lacking. Yet the characterization of best approximations is nevertheless very closely related to Property NS. Three examples are given below which illustrate this situation. The aim of this chapter is to generalize unisolvence and related concepts and to develop a theory for these situations.

2. The following examples illustrate different forms of $F$ which do not have Property NS but for which a simple theorem characterizing best approximations can be given.

**EXAMPLE 1: Polynomial Ratios.** $F$ is of the form

$$s(x) \left( \sum_{k=0}^{n} a_k x^k \right) / \left( \sum_{k=n+1}^{n+m+2} a_k x^{k-n-1} \right)$$

where $s(x) > 0$ and is continuous on $[0,1]$. Since the numerator and denominator may be multiplied by a common factor it is assumed that $\sum_{k=1}^{n+m+2} (a_k)^2 = 1$. $F$ is, then, taken to be the subset of the unit sphere of $\mathbb{R}^{n+m+2}$ for which

$$\sum_{k=n+1}^{n+m+2} a_k x^{k-n-1} \neq 0 \text{ for } x \in [0,1].$$

The classical theorem characterizing best approximations is ([1], Chapter 2):
\[
F(a, x) = s(x)\left(\sum a^i x^{n-\alpha} + \cdots + a^n\right) \div \left(\sum b^j x^{m-\beta} + \cdots + b^m\right)
\]

where \(0 \leq \alpha \leq n, 0 \leq \beta \leq m, b^m \neq 0, a^n \neq 0, b^m \neq 0\) is the best approximation to \(f(x)\) if and only if \(\max |F(a, x) - f(x)|\) alternates at least \(m+n+2-d\) times where \(d = \min(\alpha, \beta)\); if \(F(a, x) \equiv 0\) then \(d = m\).

At points of \(P\) where both the numerator and denominator are of lower degree there is an effective loss of parameters. This can be due either to the cancellation of common factors or to the coefficients of the leading terms being zero. It can be shown that \(F\) is not locally solvent near such points and therefore \(\max |F(a, x) - f(x)|\) cannot alternate \(m+n+2\) times for all \(f(x)\).

**EXAMPLE 2: An Exponential Function.** Let \(F\) be of the form \(a e^{2x} + a_3\) and let \(P\) be defined by \(|a_1| < \infty, |a_2| < \infty, |a_3| < \infty\). When \(a_1 = 1\) it is seen that \(F\) depends only on \(a_1 + a_3\) and \(F\) is not locally solvent near \(F = \text{constant}\).

**EXAMPLE 3: Restricted Polynomial.** Let \(F\) be a polynomial and \(P\) be taken as a proper subset of \(E_n\). For example, let \(F(a, x) = a_1 + a_2 x + a_3 x^2\) with \(|a_1| < \infty, |a_2| < 10, |a_3| \leq 1\). From Theorem 6 it follows that \(F\) does not have Property NS. \(F\) fails to be locally solvent on the boundaries of \(P\).

3. In each of these examples \(F\) fails to be locally solvent at some exceptional points of \(P\). However it is seen that there is still some degree of local solvence at these points. This leads one to the concept of degree of solvence given in the following definition:
DEFINITION 14: $F$ is solvent of degree $m$ at $a^* \in P$ if given a set $\{x_j^0 \leq x_1 < x_2 < \cdots < x_m \leq 1\}$ and $\epsilon > 0$ then there is a $\delta(a^*, \epsilon, x_1, \ldots, x_m) > 0$ such that $|y_j - F(a^*, x_j)| < \delta$ implies that there is a solution, $a \in P$, to $F(a, x_j) = y_j$, $j = 1, 2, \ldots, m$ with $\max |F(a, x) - F(a^*, x)| < \epsilon$.

Thus, the degree of solvence may vary from point to point in $P$. The definitions of Properties NS and Z may be generalized in an analogous manner.

DEFINITION 15: $F$ has Property NS of degree $m$ at $a^* \in P$ if, for every $f(x)$, the alternance $m$ times of $\max |F(a^*, x) - f(x)|$ is a necessary and sufficient condition for $F(a^*, x)$ to be a best approximation to $f(x)$. A point, $a^* \in P$, is said to be of degree $m$ if $F$ has Property NS of degree $m > 0$ at $a^*$.

DEFINITION 16: $F$ has Property Z of degree $m$ at $a^* \in P$ if for any $a \neq a^*$, $F(a^*, x) - F(a, x)$ has at most $m-1$ zeros.

DEFINITION 17: $F$ is unisolvent of degree $m$ at $a^* \in P$ if

i) $F$ has Property Z of degree $m$ at $a^*$ and $F$ is solvent of degree $m$ at $a^*$; ii) $F$ is not solvent of degree $m+1$ at $a^*$.

The analog of the classical statement characterizing best approximations is: Let $a^*$ be of degree $m$, then $F(a^*, x)$ is a best approximation to $f(x)$ if and only if $\max |F(a^*, x) - f(x)|$ alternates $m$ times.
4. The aim of this section is to relate the degree of a point in \( P \) and the degree of unisolvent of \( F \) at that point.

**Lemma 16:** If \( P \) is connected and if the degree is defined for every point of \( P \) then given \( a^* \in P \) there is an \( \epsilon > 0 \) such that \( (x, F(a^*,x) \pm \epsilon) \in R \) for all \( x \in [0,1] \).

**Lemma 17:** If \( P \) is connected and if \( F \) is solvent of positive degree at every point of \( P \) then \( R = R_0 \).

These two lemmas may be proved by a slight modification of the proofs of Lemmas 8 and 9.

**Lemma 18:** Let \( F \) be closed and let \( F \) be unisolvent of positive degree at every point of \( P \). If \( F \) is unisolvent of degree \( m \) at \( a^* \) then the degree of \( a^* \) is \( m \).

This lemma may be proved by a slight modification of the proofs of Lemmas 2 and 14.

The converse of Lemma 18 is more difficult. A series of lemmas will be established which culminate in Lemma 22 which is the converse of Lemma 18. The following lemma is a generalization of Lemma 3.

**Lemma 19:** Let the degree be defined for every point of \( P \). If \( a^* \) is of degree \( m \) then \( F \) has Property Z of degree \( m \) at \( a^* \).
PROOF: Assume there is an \( a \in P \) such that \( F(a,x) - F(a^*,x) \) has \( m \) or more zeros. Then as in the proof of Lemma 3 there is a continuous function, \( f_1(x) \), such that \( \max |F(a^*,x) - f_1(x)| \) alternates exactly \( m \) times, \( \max |F(a,x) - f_1(x)| \) alternates exactly \( m-2 \) times and \( \max |F(a^*,x) - f_1(x)| = \max |F(a,x) - f_1(x)| \). Let \( f_2(x) \) be the continuous function analogously defined so that \( \max |F(a^*,x) - f_2(x)| \) alternates exactly \( m-2 \) times, \( \max |F(a,x) - f_2(x)| \) alternates exactly \( m \) times and \( \max |F(a^*,x) - f_2(x)| = \max |F(a,x) - f_2(x)| \).

Since \( a^* \) is of degree \( m \), \( F(a^*,x) \) is a best approximation to \( f_1(x) \) and hence \( F(a,x) \) is also a best approximation to \( f_1(x) \). Therefore the degree of \( a \) is less than or equal to \( m-2 \). Hence \( F(a,x) \) is a best approximation to \( f_2(x) \) and so is \( F(a^*,x) \). But since \( \max |F(a^*,x) - f_2(x)| \) alternates exactly \( m-2 \) times \( a^* \) cannot be of degree \( m \).

The following lemma is the generalization of Lemma 11 and has the same proof as Lemma 11.

**Lemma 20:** Let \( F \) be closed and let the degree be defined for every point of \( P \). Then given \( a^* \in P, \epsilon > 0 \) and a set \( \{ x_j | 0 = x_0 < x_1 < x_2 < \cdots < x_{n+1} = 1 \} \) there are \( a_1, a_2 \in P \) such that i) \( F(a^*,x) - F(a_1,x), F(a^*,x) - F(a_2,x) \) change sign at the \( x_j \) and at no other points, ii) \( |F(a_1,x) - F(a^*,x)| \leq \epsilon, |F(a_2,x) - F(a^*,x)| \leq \epsilon \), iii) either \( F(a_1,x) - F(a^*,x) = 0 \), \( F(a_2,x) - F(a^*,x) = 0 \) or \( \text{sgn}[F(a_1,x) - F(a^*,x)] = -\text{sgn}[F(a_2,x) - F(a^*,x)] \).
The next lemma shows an interesting property of some special subsets of \( P \) and provides a means of generalizing Lemmas 12 and 13.

**Lemma 21:** Let \( F \) be closed and let the degree be defined for every point of \( P \). Define \( P_k = \{ a | a \in P, \deg a \geq k \} \). Then \( P_k \) is an open set.

**Proof:** Let \( a^* \in P_k \) be given. By Lemma 20 there is an \( a_1 \in P \) such that \( F(a^*, x) - F(a_1, x) \) has \( k-1 \) zeros in the interior of \([0, 1]\). Let \( \{x_j | j = 1, 2, \ldots, k-1, x_j < x_{j+1}\} \) be the set of these zeros and set \( x_0 = 0, x_k = 1 \). Let \( \delta = \min_j \max_{x \in [x_j, x_{j+1}]} |F(a^*, x) - F(a_1, x)| \). It is clear that for any \( a \in P \) if \( \max_j |F(a, x) - F(a^*, x)| < \delta \) then \( F(a, x) - F(a_1, x) \) has at least \( k-1 \) zeros.

Since \( F \) is continuous there is a neighborhood of \( a^* \), \( N(a^*) \), such that if \( a \in N(a^*) \) then \( \max_j |F(a, x) - F(a^*, x)| < \delta \) and \( F(a, x) - F(a_1, x) \) has at least \( k-1 \) zeros. By Lemma 19 the degree of \( a \) is larger than or equal to \( k \).

**Lemma 22:** Let \( F \) be closed and let the degree be defined for every point of \( P \). If \( a^* \) is of degree \( m \) then \( F \) is unisolvent of degree \( m \) at \( a^* \).

**Proof:** Let \( \delta \) be the quantity defined in the proof of Lemma 21 and set \( \Delta = \{(x, y) | x \in [0, 1], |F(a^*, x) - y| < \delta \} \). From the proof of Lemma 21 it is seen that every \( F(a, x) \) entirely in \( \Delta \) is of degree \( m \) or more. Lemma 22 is now proved by restricting consideration to functions entirely in \( \Delta \) and by using the proofs of Lemmas 12 and 13.
The statement of the generalization of Lemma 12 is: "Let \( F \) be closed and let the degree be defined for every point in \( P \). Let \( a^* \in P \) be given with degree \( m \) and let \( F(a^*, x) - F(a, x) \) change sign at \( m-1 \) points with \( F(a, x_o) \neq F(a^*, x_o) \) and let \( \max|F(a^*, x) - F(a, x)| \leq \delta \). Then given \( y \) between \( F(a, x_o) \) and \( F(a^*, x_o) \) there is an \( a_o \in P \) such that \( F(a_o, x_o) = y \) and \( F(a_o, x) \) is between \( F(a, x) \) and \( F(a^*, x) \)." The only part of the statement that is not a straightforward generalization of Lemma 12 is the condition that \( \max|F(a^*, x) - F(a, x)| \leq \delta \). This condition implies that \( a \) is of degree \( m \) or more and the proof of Lemma 12 may be used to prove this generalization of Lemma 12.

The generalization of Lemma 13 may be proved with a slight modification of the proof of Lemma 13. In the induction argument of the proof it is merely necessary to take \( \epsilon < \delta \) and the same proof is valid for the generalization.

In view of Lemma 19, this concludes the proof of Lemma 22.

The preceding lemmas have established

**THEOREM 7:** If \( F \) is closed then the following statements are equivalent:

i) \( F \) is unisolvant at every point of \( P \) and is unisolvent of degree \( m \) at \( a^* \).

ii) The degree is defined for every point of \( P \) and the degree of \( a^* \) is \( m \).
5. Theorem 7 directly relates the characterization of best approximations to the degree of insolventence of $F$. Since insolventence is directly connected with the explicit definition of $F$ this gives a natural means of studying the characterization of best approximations.

It is interesting to examine the variation of the degree for the three examples previously considered.

**EXAMPLE 1:** Let $P_k = \{ a | a \in P, \ a^n = \cdots = a^{n-k} = a^{n+m} = \cdots = a^{n+m-k} = 0 \}$ and $P' = \{ a | a \in P, \ a^n = a^{n-1} = \cdots = a^0 = 0 \}$. If $a \in P_k$, $a \not\in P_{k+1}$ then the degree of $a$ is $n+m-k$ and if $a \in P'$ the degree of $a$ is $n+1$. If $a$ is in none of these sets then the degree of $a$ is $n+m+1$.

**EXAMPLE 2:** Every point of $P$ is of degree 3 except those for which $a_2 = 1$; these points are of degree 2. Note that $F$ is not closed in this example for as $a_2 \to \infty$ the limiting function is discontinuous. However, it can be shown that the theory developed here is still valid.

**EXAMPLE 3:** The interior points of $P$ are of degree 3. The interior points of the two dimensional faces are of degree 2 and the points on the one dimensional edges are of degree 1.

In this example if $P$ were defined by $|a^1| < \infty$, $|a^2| < 10$, $|a^3| < 1$ then $F$ would have Property NS with $n = 3$. However best approximations would not exist for every continuous function as they do with the present definition of $P$. 
REFERENCES


