EXPERIMENTAL INVESTIGATION OF DETACHED SHOCK ON A 70° CONE AT VARIOUS ANGLES OF ATTACK

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ABS TRACT

The results of an experimental investigation into the variation of the shock wave shape and the extent of the subsonic region behind the shock with varying angle of attack at various Mach numbers are summarized. All tests are made on a finite 70° cone. The main interest is centered on those Mach numbers which are low enough to produce detached shocks or for which the possibility of detachment exists for increasing angles of attack.

The angles of attack for which the investigation is made are 0°, 3°, 6°, 9°, 12°, and 15°. The Mach numbers considered are 1.438, 1.544, 1.584, 1.857, 1.986, and 3.01.

It is found that, for increasing angles of attack at constant Mach numbers, the extent of the subsonic region increases behind the lower shock and decreases behind the upper shock. A subsonic region appears at increased angle of attack for two of the Mach numbers for which the shocks are initially attached. There is also quite definite interaction between the upper and lower portions of the shock which tends to inhibit both the appearance of a subsonic region after the shock on the one hand and the disappearance of it on the other.

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I. INTRODUCTION

The general objective of this investigation was the experimental determination of the shock wave shape and its allied characteristics due to the presence of a finite, 70° cone in a supersonic flow at various angles of attack. The main interest was to be centered on detached shocks and those attached shocks for which there was a possibility of detachment occurring as angle of attack was increased, and particular interest was to be given to the subsonic regime of flow behind the shock. Pressure measurements at the cone surface were not to be attempted extensively, but were desired only for one Mach number at zero angle of attack and at a relatively high angle of attack.

As far as is known, no previous experimental work has been done on detached shock variations with angle of attack for three-dimensional flow. B. W. Marschner, (Cf. Ref. 1), V. I. Muirhead, and Neil MacKinnon, (Cf. Ref. 2), have previously investigated detached shock wave shapes, Mach number behind the shock, and pressure distribution for similar cones throughout the same range of Mach numbers at zero angle of attack. This investigation was intended to carry their work one step further.

Since theoretical study of the detached shock phenomenon has not yet progressed to the point where a prediction of the behaviour of shock waves at various angle of attack can be made, this investigation, it was hoped, would furnish some small insight into this interesting phase of supersonics, and perhaps point the way to further study.

II. EQUIPMENT AND PROCEDURE

Six cone models were used for this investigation. The models were identical, 3/8ⁿ in diameter, and had a cone angle of 70° . Each model was equipped with a pressure orifice located on the conical surface at distances from the nose which varied from model to model. The dimensions of the cone model and the location of the pressure orifices are indicated in Fig. 1.

The investigation was carried out in the GAICIT 2.5" Supersonic Wind Tunnel, (Cf. Ref. 3). The model was mounted on a sting which could be moved in elevation through an angle of attack range from -3° to +15°. No azimuthal variation was possible. In order to produce Mach numbers of 1.438, 1.544 and 1.857 a flexible nozzle with adjustable jacks was used. This nozzle is fully described in Ref. 1. Steel nozzle blocks were available for Mach numbers of 1.584, 1.986 and 3.01. The nozzle shapes for the flexible nozzle were computed by Puckett's Method, (Cf. Ref. 4). Boundary layer corrections were applied using Puckett's approximate figure.

In order to calibrate the test section Mach number a static pressure survey was made along the nozzle centerline in conjunction with a reference static pressure taken at the test section wall. The centerline survey was accomplished with a section of I.D. 0.065" tubing fixed by means of two rigid supports at either end of the nozzle so that movement

was possible in an axial direction only. This tubing was equipped with a small static orifice. In order to eliminate the necessity for measuring small changes in low pressure along the test section centerline against a relatively high atmospheric pressure, the centerline static pressure was measured against the reference pressure at the wall. The reference pressure was, in turn, measured against atmospheric pressure. By subtracting the difference in wall and centerline pressures from the average wall pressure the centerline static pressure was obtained.

In calibrating the model angle of attack the following procedure was used. Pressure readings were taken at three angles of attack with the model orifice on the top. Pressure readings at the same three angles of attack were then taken with the orifice on the bottom. These pressure readings were plotted against angle of attack; thus, intersection of top and bottom curves gave the zero angle of attack position.

Throughout the tests the relative humidity of the tunnel was kept within a range of .02 to .04 percent by means of a silica-gel dryer in the tunnel circuit.

After calibration of the nozzle and angle of attack, photographs of the flow around the model were taken by means of schlieren apparatus with the model at angles of attack varying from 0° to 15° in 3° increments.

Finally, a pressure survey at the cone surface was made at a Mach number of 1.584 for angles of attack of 0° and 12° , (Cf. Fig. 27).

The dimensionless shock wave patterns were obtained by the following procedure. The negatives of the flow photographs were projected on graph paper by means of a photographic enlarger. The enlarger was adjusted so that the diameter of the model was equal to a Y/D of one on the selected scale, and the shock wave pattern was traced. This same procedure was followed in tracing all shock wave patterns. In order to minimize the error in the relative displacement of the shocks from the model from one angle of attack to the next, all shock patterns for each particular Mach number were traced on the same sheet of graph paper. This procedure was also followed for each particular angle of attack and varying Mach number. The final dimensionless plots were obtained directly from these tracings. It was hoped, by this means, to minimize, in so far as was possible, the errors which are inevitable in transcribing such curves to dimensionless coordinates.

III. RESULTS AND DISCUSSION

The results of this investigation are presented in three forms. The shock wave patterns are plotted first with Mach number constant and angle of attack varying, (Cf. Figs. 3 to 14). Secondly, they are plotted with angle of attack constant and Mach numbers varying, (Cf. Figs. 15 to 25). The above plots are relative to the cone axis rather than to the flow direction. Thirdly, the Mach number (M2) directly behind the shock is tabulated for each Mach number and angle of attack, (Cf. Tables I to VI). This tabulation is carried out only for the subsonic portion of the flow. In addition to the above tabulation, the point at which the Mach number behind the shock becomes sonic and the position of the normal shock are indicated on the shock wave plots. For Mach numbers of 1.357 and 1.986 the sonic points have not been indicated, to avoid confusion. These points are, however, indicated on the cross-plots of constant angle of attack.

A pressure survey on the surface of the cone at a Mach number of 1.584 was taken at 0° and 12° angles of attack for both upper and lower surfaces of the cone. (Cf. Fig. 27).

Symbols used in graphical and tabular presentation of the data are defined in Fig. 2.

The shock wave patterns were plotted in dimensionless form using the diameter of the cone as the characteristic dimension. Special care

was taken in obtaining the shape of the shock wave patterns near the nose of the cone since it was found that some of the shocks crossed in this region.

The shock wave patterns for constant Mach number show that close to the nose of the cone, the spread of the shocks is rather irregular with some crossing over others in an unpredictable manner; the spread, however, becomes regular with angle of attack as the distance from the nose along the shock increases. This is particularly true of the lower portions of the shock waves. As the angle of attack increases, the shocks associated with the upper surface of the cone tend to become straight and to assume the characteristics of an attached shock. Conversely, the lower portion of these shocks become more curved and thus more nearly assume detached characteristics. This is more clearly brought out by the Mach number survey directly behind the shock.

The variations in the shock wave pattern due to changing Mach number are plotted for each angle of attack, and are essentially a cross-plot of the previously discussed curves. These plots clearly show that, while the lower portions of the shocks gradually assume the curved configuration associated with detached shocks as the angle of attack increases, those shocks which were initially physically attached to the nose of the cone apparently remain attached for the angles of attack investigated. Conversely, shocks initially physically detached remain detached.

The Mach number directly behind the shock at each point under consideration was calculated by measuring the slope of the shock at that point relative to the flow direction. Two-dimensional oblique shock theory then gave the Mach number behind the shock, (Cf. Tables I to VI).

At an angle of attack of 0°, the subsonic region behind the shock is symmetrical with respect to the cone axis. As the angle of attack increases for each Mach number, the extent of the subsonic region increases behind the lower portion of the shock and decreases behind the upper portion. The rate of decrease, however, is considerably faster than the rate of increase. The overall effect is to decrease the total extent of the subsonic region as the angle of attack is increased. This effect is more pronounced for the lower Mach numbers. As the Mach number increases at each angle of attack the extent of the subsonic zone decreases in both the lower and upper portions of the flow.

If the assumption is made that the cone upper and lower surfaces can be considered separately and that the angle between the flow direction and the cone surface can be considered as the half-vertex angle of a fictitious cone, some comparison can be made with the Taylor-Maccoll theory for conical shocks, (Cf. Ref. 5). Fig. 26 was prepared to illustrate the maximum flow deflection for a given initial Mach number using this theory. Table VII indicates the condition of

shock for each Mach number for both upper and lower shocks.

First considering the lower shocks at zero angle of attack. the shock has detached characteristics until a Mach number between 1.534 and 1.857 is reached, where it assumes attached characteristics. This is in agreement with the Taylor-Maccoll theory. The results also agree for 30. At an angle of attack of 60, which corresponds to a fictitious cone with a half-vertex angle of 41°, the Taylor-Maccoll theory gives the minimum Mach number for an attached shock as 2.03. The experimental results indicate that for an angle of attack of 60 the flow field behind the lower shock has a subsonic region for Mach numbers to 1.857. The lower shock for a Mach number of 1.986, however, does not have a subsonic region and thus has attached characteristics. The subsonic region for a Mach number of 1.986 does not appear until an angle of attack of 90 is reached. These subsonic regions behind the lower shock increase with increasing angle of attack. For a Mach number of 3.01, the conical shock theory predicts that shock detachment will occur at a half-vertex angle of something less than 50°, corresponding to an angle of attack of less than 150. However, experimental results indicate that at an angle of attack of 150 the shock still has attached characteristics; no subsonic zone is present.

The upper portion of the shock can be considered in the same manner. In this case the fictitious half-vertex angle can be considered

as decreasing as the angle of attack increases. The conical shock theory predicts that at an angle of attack of approximately 6° corresponding to a half-vertex angle of 29°, the shock will become attached for the Mach numbers investigated. The experimental results indicate that, for the angles of attack investigated, if a subsonic zone initially exists it does not wholly disappear.

It therefore is apparent that interaction does exist between the upper and lower portions of the shock wave in conical flow at angles of attack. This interaction inhibits or delays the disappearance of the subsonic region behind the upper shock and delays the appearance of the subsonic region behind the lower shock as angle of attack is increased. Stated differently, this interaction decreases the ability of the shock to deflect the flow in the upper portion of the shock and increases this same ability in the lower, as compared to that predicted by the Taylor-Maccoll theory.

The cone surface pressure measurements at a Mach number of 1.584 were reduced to the non-dimensional form $p_{\rm s}/p_{\rm o}$, where $p_{\rm o}$ is the reservoir pressure behind the normal shock. The plot of these measurements are included to indicate the variation of the cone surface pressure at angles of attack of 0° and 12°, (Cf. Fig. 27).

IV. CONCLUSTONS

The results of this investigation indicate that at angles of attack there is interaction between the upper and lower portions of the shock. This interaction tends to delay the appearance of a subsonic region behind the lower portion of the shock and to delay the disappearance of the subsonic region behind the upper portion of the shock. The delay in the disappearance is greater than the delay in the appearance.

It is also indicated that the extent of the total subsonic region is reduced as the angle of attack is increased for those Mach numbers which initially produce detached shocks.

Finally, it appears that if the shock is initially attached to the cone it remains attached even though mixed flow appears behind the shock, for the range of angles of attack tested.

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SAMPLE CALCULATIONS

A. Determination of Mach number in test section:

pog = gauge reservoir pressure

p₂ = reference wall static orifice pressure

 $p_{2_{r}} = gauge reference pressure$

 p_{x} = nozzle centerline static orifice pressure

Density conversion factors:

 p_2

1 cm. acetylene tetrabromide = .2188 cm. hg.

1 cm. silicone

= .0695 cm. hg.

$$\frac{p_x}{p_0} = \frac{p_2}{p_0} - \frac{p_2 - p_x}{p_0}$$

Orifice position	1.8"
p_{o_g}	103.0
Pa	93.3
Pog - Pa	9.7
.2188 (p _{og} - p _a)	2.12
Barometer	74.57
Po	72.45
pa	73.15
P ₂ g	129.6
p = p ₂	56.45

18,12

P ₂ /P _a (av.)	.2487
P ₂	69.6
$P_{\mathbf{x}}$	64.0
p ₂ - p _x	-5. 6
.0695 (p ₂ - p _x)	∞. 389
.0695 $(p_2 - p_x)/p_0$	00537
p_x/p_o	.2541
M	1.544

B. Determination of p_s/p_0^{t} , M = 1.584

p_s = surface pressure on cone

po' = reservoir pressure behind normal shock

$$p_{s}/p_{o}' = \frac{p_{s}}{p_{o}} \times \frac{p_{o}}{p_{o}}'$$

 $p_{\rm s}/p_{\rm o}$ was found in the same way as in the determination of the Mach number.

p _s /p _o	.591
po/po'	1.109
ps/po'	.655
x*	.2497"
S	.32 ¹¹
x' /S	.779

TABLE I

$\alpha = 0^{\circ}$			$\alpha = 3^{\circ}$					
Upper	and Lower	$v_{\rm j}$	pper	Lo	wer			
Y/D	M ₂	Y/D	M ₂	Y/D				
0	.730	0	. 730	0	.736			
•2	.780	.2	•308	.03	.735			
.4	.825	•4	.865	.2	.769			
•6	.865	•6	.895	•4	.822			
•8	• 905	.8	.942	•6	.865			
1.0	. 942	1.0	.990	.8	.900			
1.2	.974	1.12	1.000	1.0	.927			
1.4	.999			1.2	• 958			
1.41	1.000			1.4	.991			
				1.47	1.000			

TABLE I (continued)

$\alpha = 6^{\circ}$				α	= 9°		
Upper		Lo	wer	Up	Upper		wer
Y/D	M ₂	Y/D	M ₂	Y/D	M ₂	Y/D	M ₂
0	.748	0	.748	0	• 750	0	. 750
.2	.800	.04	.735	. 2	.835	•09	. 735
•4	.885	• 2	.760	•4	.895	.2	.765
•6	.920	.4	.817	•6	. 920	•4	• 795
.8	. 960	•6	.860	.8	. 955	. 6	.815
1.0	. 990	.8	.900	1.0	.990	.8	.838
1.08	1.000	1.0	. 934	1.02	1.000	1.0	.862
		1.2	•960			1.2	.900
		1.4	•985			1.4	.942
		1.58	1.000			1.59	1.000

TABLE I (continued)

	<u>c</u> =	= 12°				<u>a</u>	= 150	
ΰρ	per	Lo	wer -		Up:	per	Lo	wer
Y/D	M ₂	Y/D	M_2	Y,	/D	M_2	Y/D	$\underline{M_2}$
0	.770	0	.770	()	.812	0	.812
.2	. 850	.12	.735	• 4	2	.880	.185	.735
•4	.920	.2	.750	.	1	.940	.2	.735
•6	.930	• 4	.775	 (3	.985	<u>.</u> 4	.760
.8	.990	•6	.797	d	735	1.000	•6	.798
. 85	1.000	3.	.860				3.	.845
		1.0	.890				1.0	.894
		1.2	. 943				1.2	.937
		1.4	.995				1.4	.975
		1.44	1.000				1.57	1.000

TABLE II

$\alpha = 0^{\circ}$			$\alpha = 3^{\circ}$					
Upper s	and Lower	$\mathtt{U}_{\mathtt{E}}$	per	Lo	wer			
Y/D	M ₂	Y/D	M_2	Y/D				
0	. 695	0	.700	0	. 700			
.2	. 355	•2	.828	.02	.695			
•4	.887	• 4	.860	.2	.770			
•6	.895	.6	.920	.4	.832			
•8	.922	.8	. 955	. 6	.880			
1.0	.970	. 98	1.000	•8	. 920			
1.15	1.000			1.0	• 958			
				1.17	1.000			

TABLE II (continued)

M = 1.544

	α =	= 6°			<u>a</u>	= 90	
Up	Upper		wer	$\mathtt{U}_{\mathtt{I}}$	pper	Lo	wer
Y/D	S_{M}	Y/D	M ₂	Y/D	M ₂	Y/D	M ₂
0	.707	0	.707	0	.720	0	.720
.2	.804	.02	.695	•2	.770	.08	.695
•4	.905	.2	.775	•4	.775	.2	.745
•6	.938	•4	. 843	•6	.946	•4	.820
8.	.963	•6	.885	8.	.992	.6	. 856
1.0	.993	8.	.910	.88	1.000	.8	.900
1.02	1.000	1.0	•960			1.0	.951
		1.12	1.000			1.18	1.000

TABLE II (continued)

	α =	120			α	= 15°	
Upj	per	Low	er	Up	per	Lo	ver
Y/D	_M ₂	Y/D	M ₂	Y/D	M ₂	Y/D	M ₂
0	.730	0	.730	0	.740	0	.740
.2	.910	.075	.695	.2	.825	.1	.695
.4	• 953	.2	.730	• 4	, 965	.2	.710
•68	1.000	•4	.780	.47	1.000	•4	.770
		•6	.835			•6	.827
		.8	.876			.8	.882
		1.0	.925			1.0	.934
		1.2	1.000			1.2	.990
						1.22	1.000

TABLE III

α	= 0°		$\alpha = 3^{\circ}$		
Upper s	and Lower	U	pper	Lo	wer
Y/D	M ₂	Y/D	M ₂	Y/D	M_{2}
0	. 685	0	•690	0	.690
•2	.867	•2	.912	•02	. 685
.4	.912	.4	. 952	.2	.815
.6	.925	•6	. 960	•4	.880
.8	.949	.8	.990	•6	.918
. 94	1.000	. 83	1.000	•8	.953
				1.0	. 980
				1.06	1.000

TABLE III (continued)

M = 1.584

	α =	= 6°			α =	= 9°	
Uр	per	Lov	ver	Up	per	Lo	wer
Y/D	M ₂	Y/D	M ₂	Y/D	$M_{\mathcal{Z}}$	Y/D	M ₂
0	.695	0	.695	0	.705	0	.705
.2	.940	.02	. 685	.2	• 990	.08	.685
•4	.947	•2	.800	•4	.996	.2	.735
. 6	.969	.4	.830	•55	1.000	.4	.800
•75	1.000	•6	.853			•6	.846
		.8	• 933			. 8	. 900
		1.0	.990			1.0	•968
		1.035	1.000			1.17	1.000

TABLE III (continued)

M = 1.584

	<u>a</u> =	120			<u>a</u>	= 15°	
Up	per	Lo	wer	1	Upper	Lo	wer
Y/D	M ₂	Y/D	M ₂	Y/1	M ₂	Y/D	M ₂
0	.700	0	.715	0	.730	0	.730
•2	.970	.07	.685	.2	.975	. C8	.685
•3	1.000	.2	.732	.2:	3 1.000	•2	.740
		4	.790			.4	.780
		•6	.837			•6	.800
		3.	.885			8.	.851
		1.0	•958			1.0	.920
		1.16	1.000			1.14	1.000

TABLE IV

M = 1.857

 $\alpha = 3^{\circ}$

Upper and Lower

 $\alpha = 0^{\circ}$

Upper and Lower

Supersonic			Supersonic			
a =	60		<u>a</u> =	= 9°		
Upper	Lo	wer	Upper	Lo	wer	
	Y/D	M ₂		Y/D	M ₂	
Supersonic	0	• 755	Supersonic	0	. 830	
	.2	. 890		.2	. 850	
	•4	•970		•4	.920	
	.6	.995		.6	.970	
	.62	1.000		.67	1.000	

TABLE IV (continued)

a = 1	12°		$\alpha = 15^{\circ}$				
Upper	Lo	wer	Upper	Lon	wer		
	Y/D	M ₂		Y/D	M ₂		
Supersonic	0	. 70	Supersonic	0	.625		
	•2	.78		.2	. 760		
	•4	. 85		•4	.790		
	•6	. 93		•6	.867		
	•75	1.00		.8	.970		
				.83	1.000		

TABLE V

$\alpha = 0^{\circ}$	c =	3°	
Upper and Lower	Upper an	d Lowe	r
Supersonic	Supers	onic	
$\alpha = 6^{\circ}$	<u>α =</u>	9°	
Upper and Lower	Upper	Lo	wer
Supersonic		Y/D	M_2
	Supersonic	0	•960
		.2	.960
		•4	•960
		•6	.972
		.64	1.000

C ====	12°		<u>a</u>	15°	
Upper	Lo	wer	Upper	Lo	wer
	Y/D	M ₂		Y/D	M ₂
Supersonic	0	.830	Supersonic	0	.790
	.2	.860		.2	.810
	.4	.895		.4	.845
	•6	.970		•6	. 866
	.68	1.000	Nakozine Walendyrickým, Strong im Fille eft en Sjánfelm	.775	1.000

TABLE VI

M = 3.01

Flow was supersonic behind shock at all angle of attack investigated.

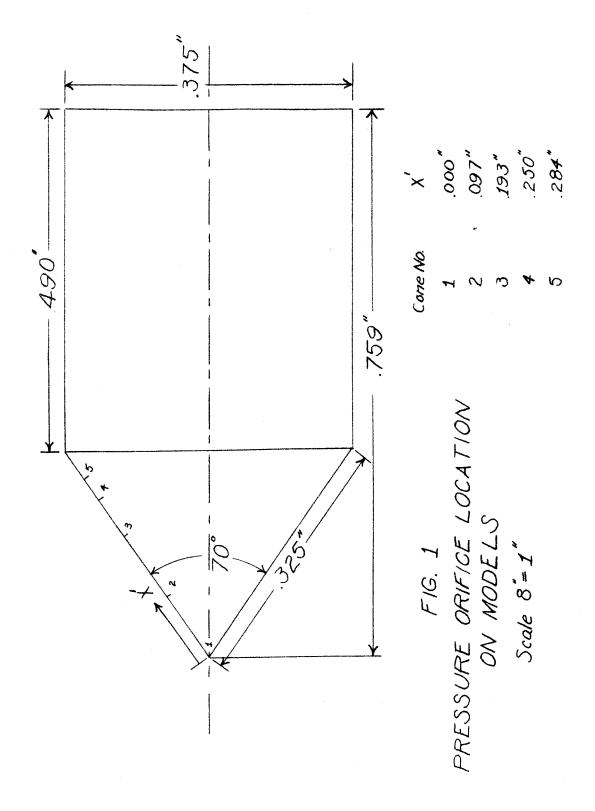
TABLE VII

CONDITION OF SHOCK

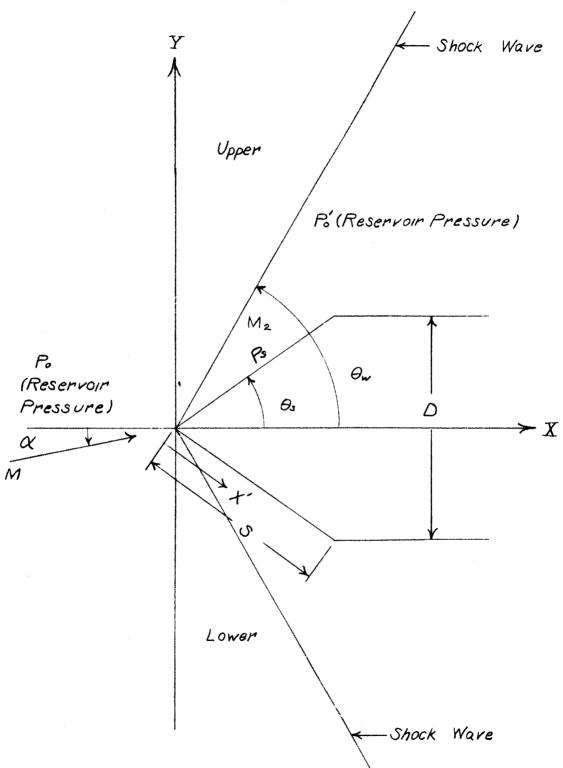
		00	3°	6 ⁰	90	120	15°
M = 1.438	Upper Lower	D D	D D	D D	D	D D	D D
M = 1.544	Upper	D	D	D	D	D	D
	Lower	D	D	D	D	D	D
M = 1.584	Upper	D	D	D	D	D	D
	Lower	D	D	D	D	D	D
M = 1.857	Upper	A	A	A	A	A	A
	Lower	A	A	D	D	D	C
M = 1.986	Upper	A	A	A	A	A	A
	Lower	A	A	A	D	D	D
M = 3.01	Upper	A A	A A	A A	A A	A A	A A

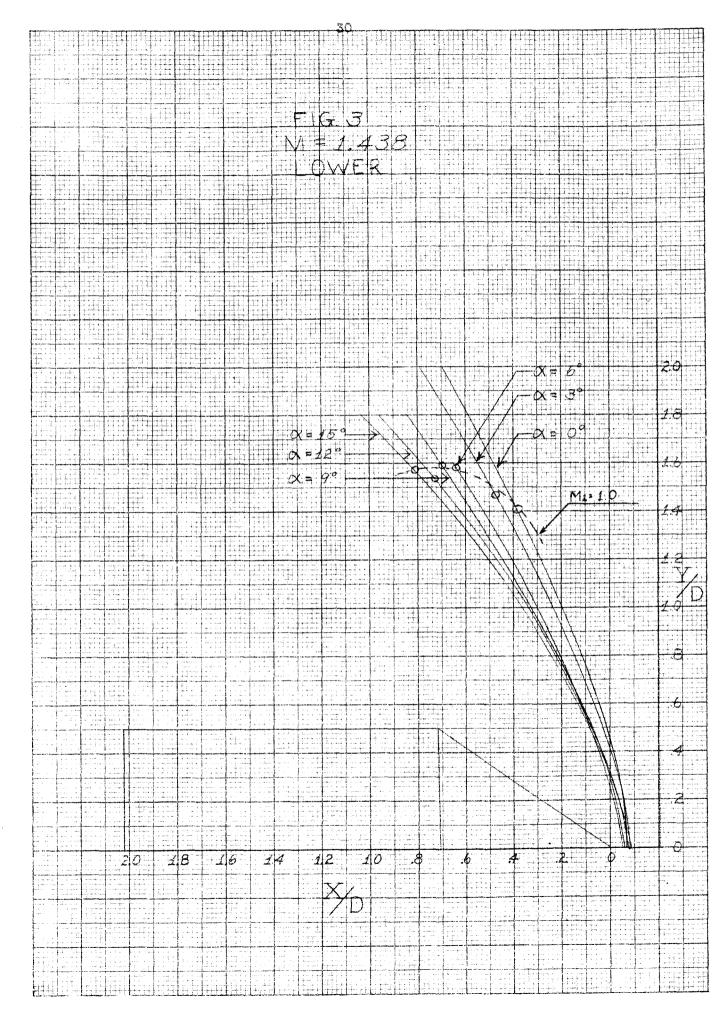
Note: D detached shock characteristics

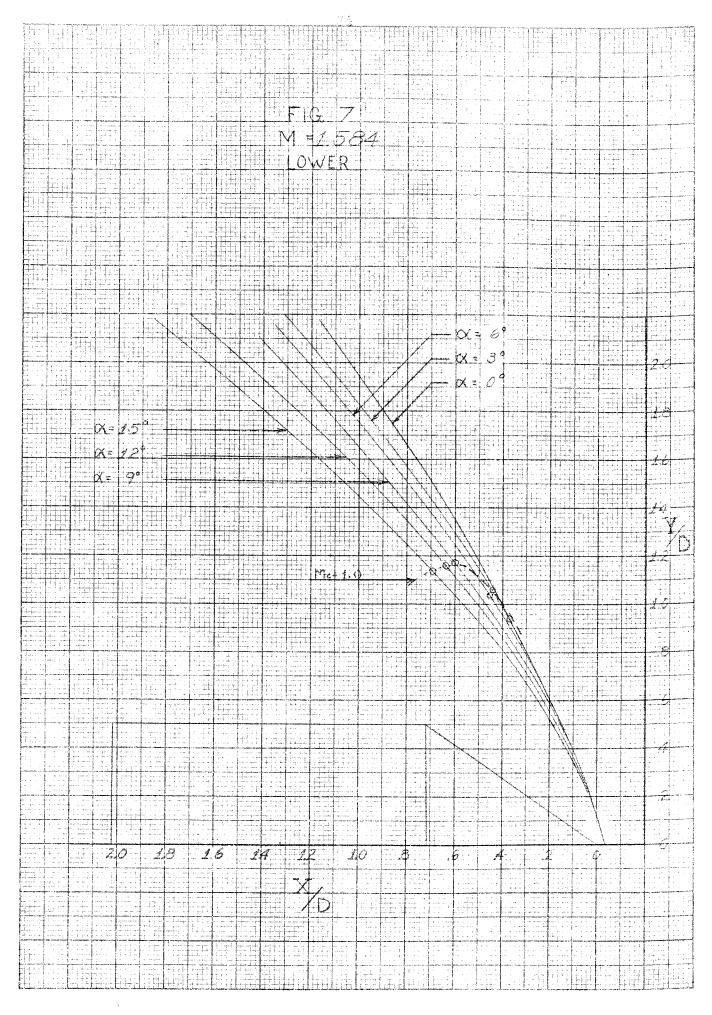
A attached shock characteristics

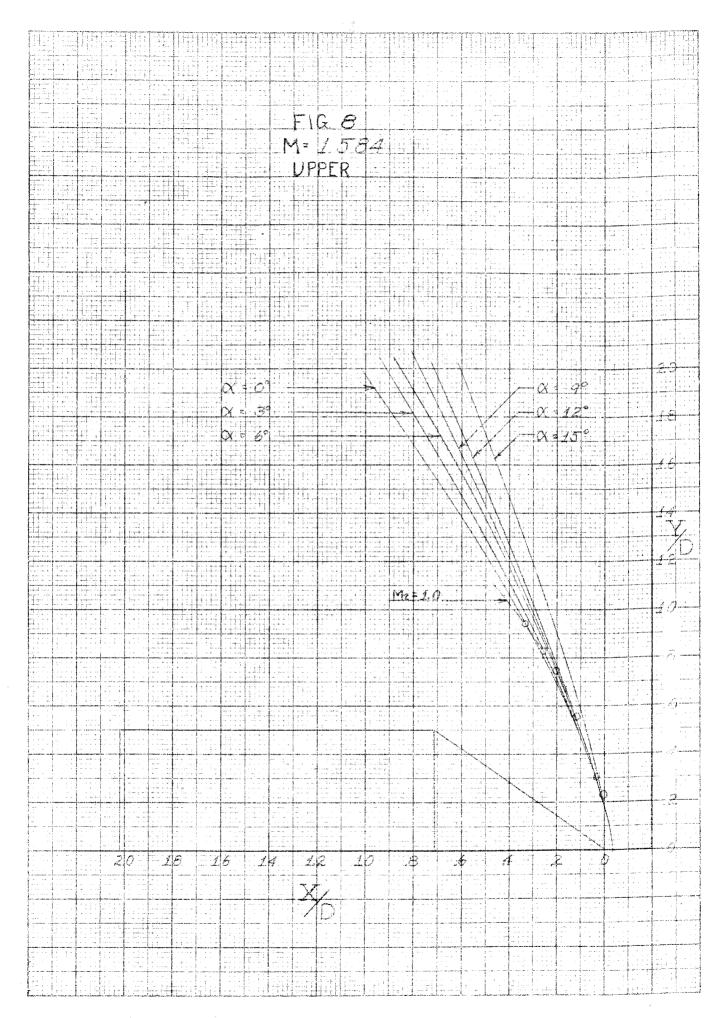


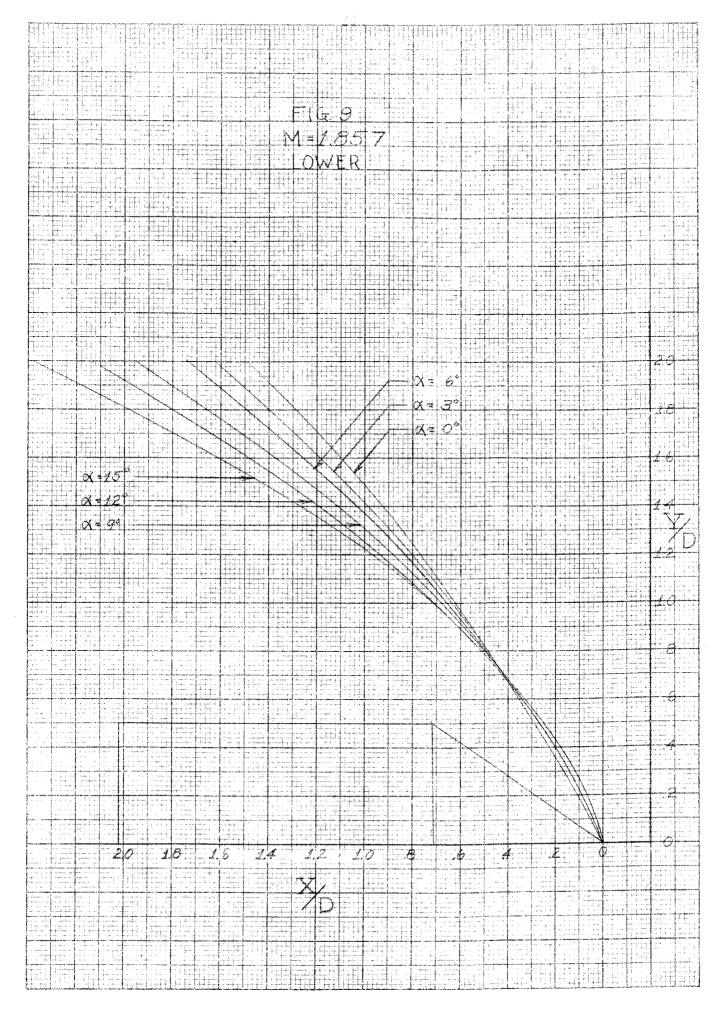


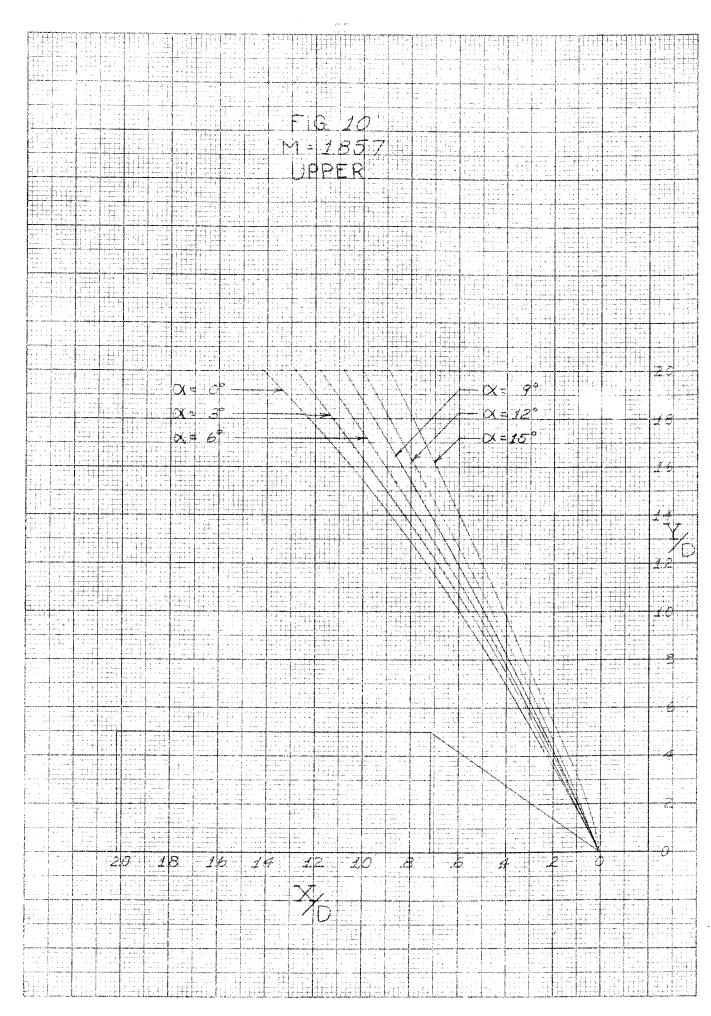


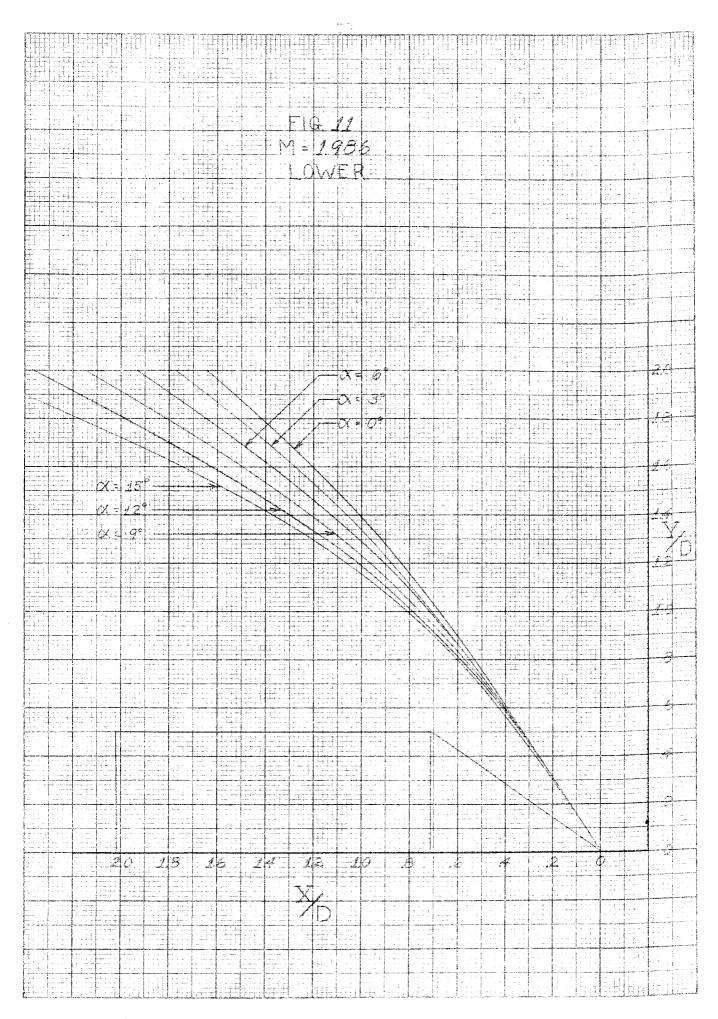


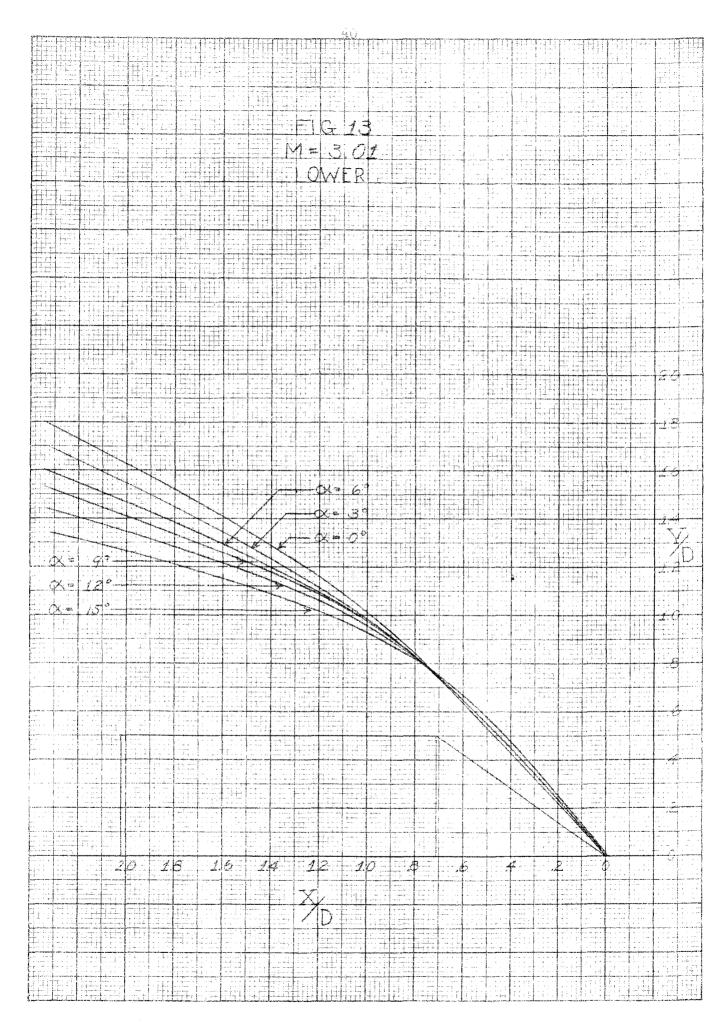


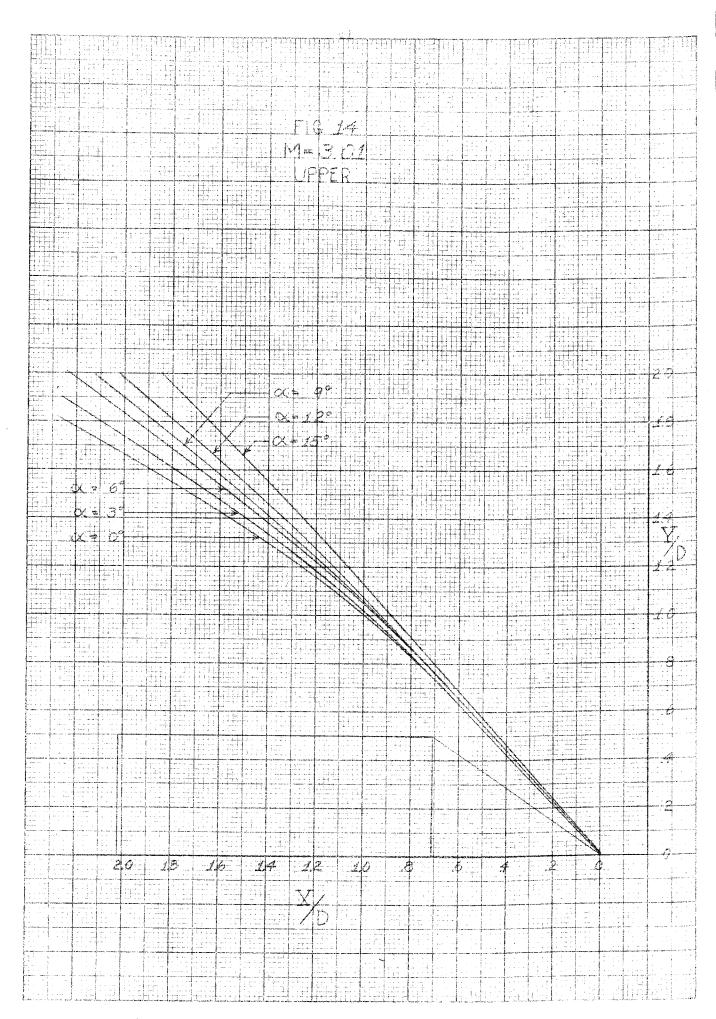


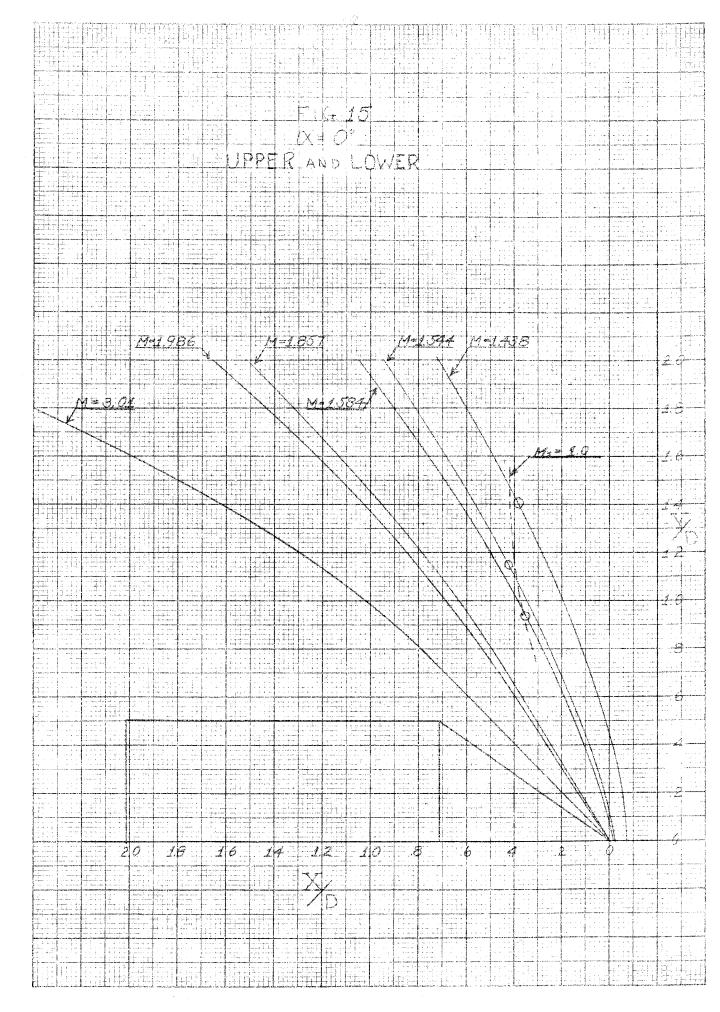


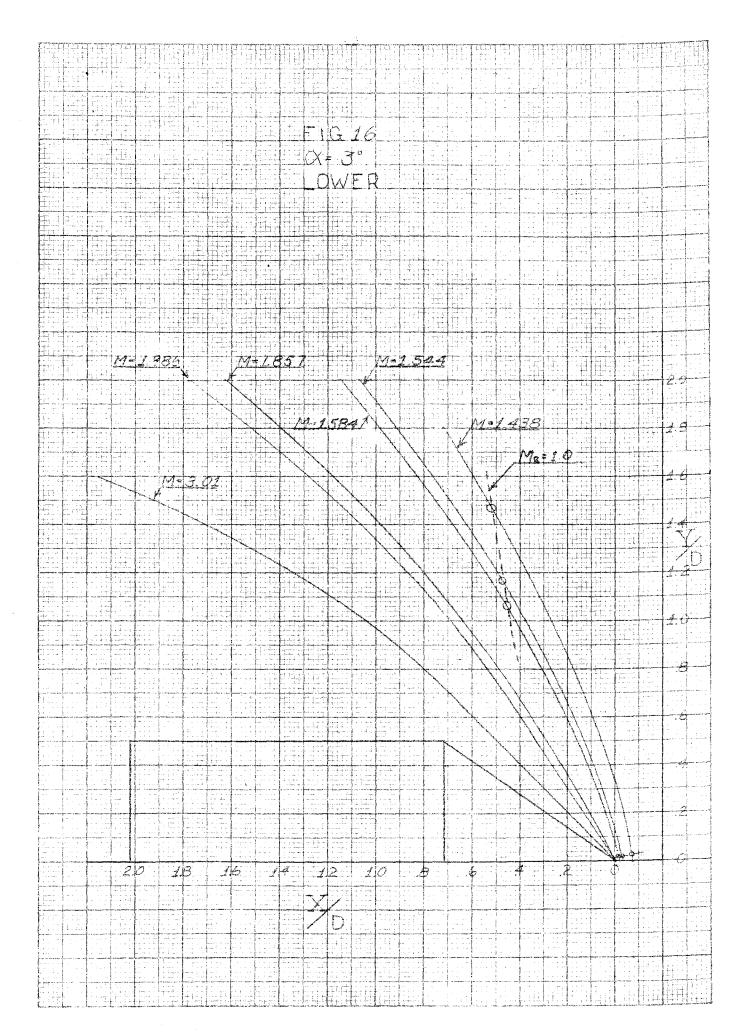


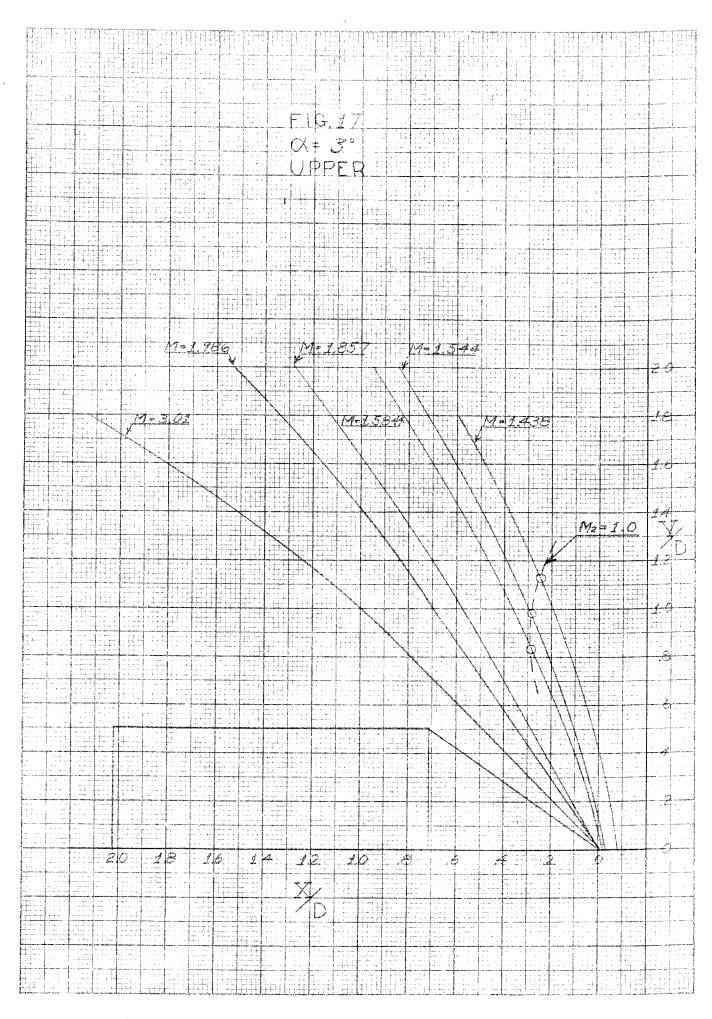


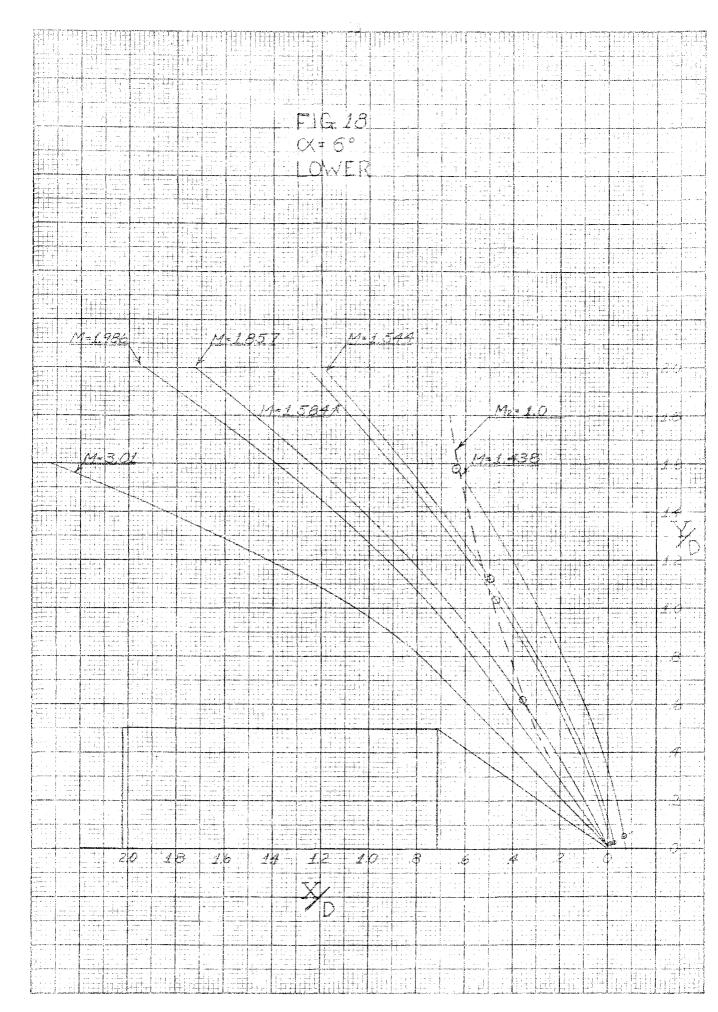


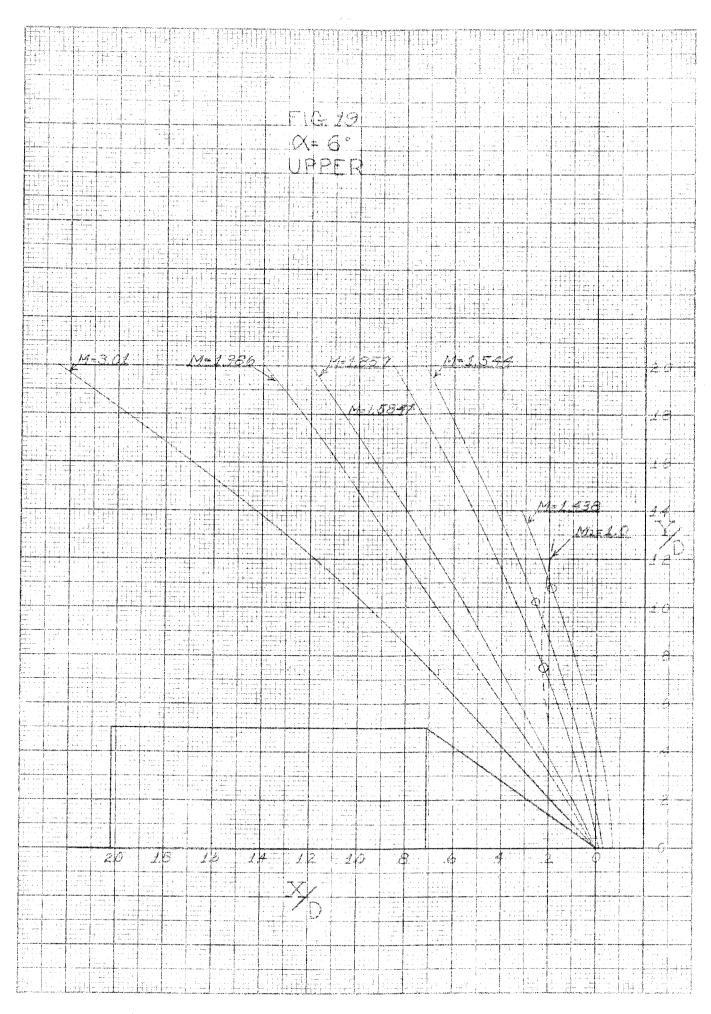


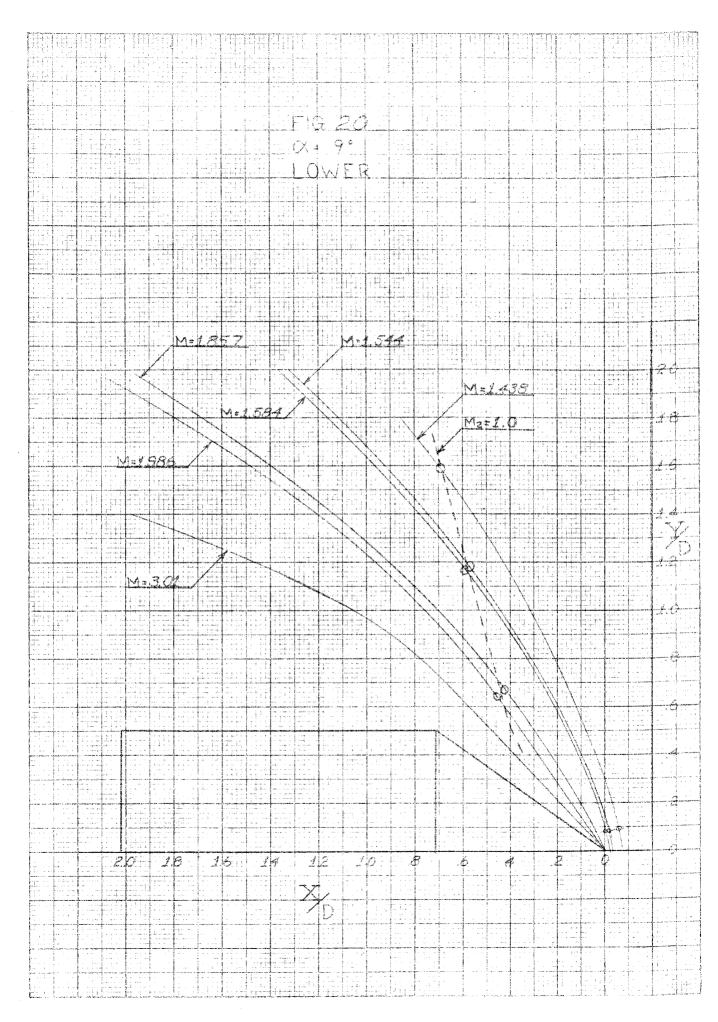


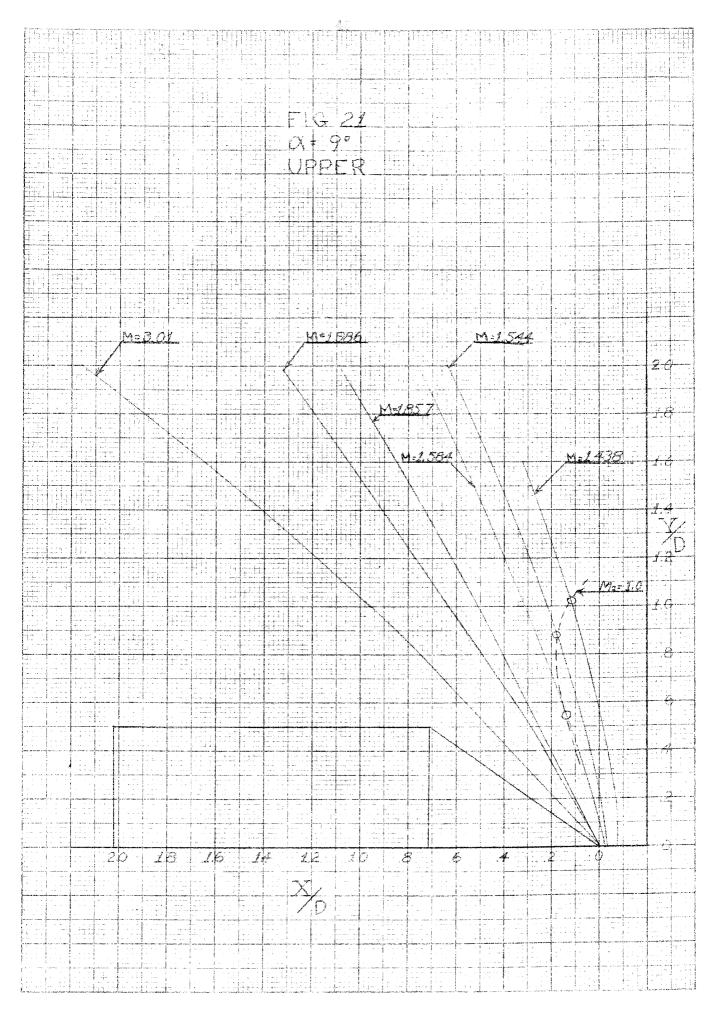


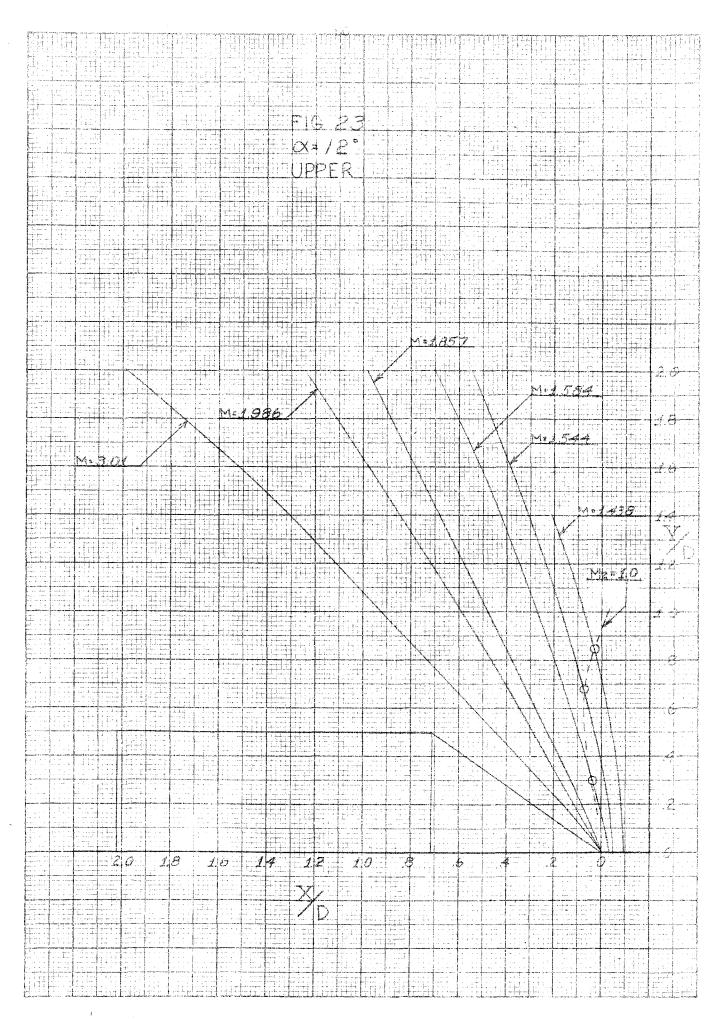


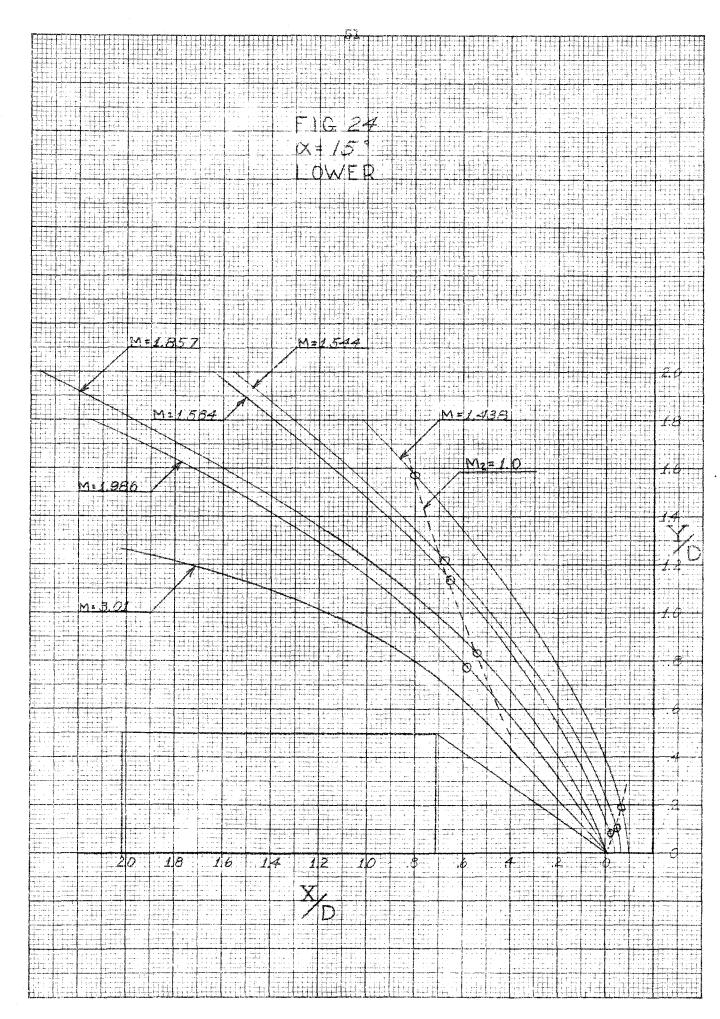


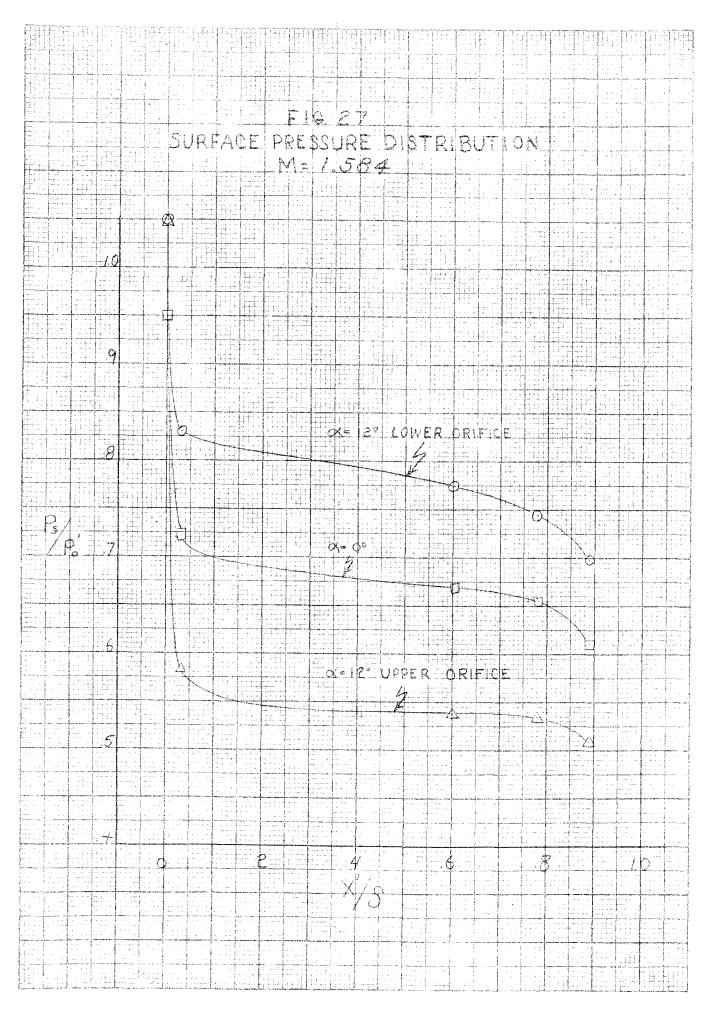












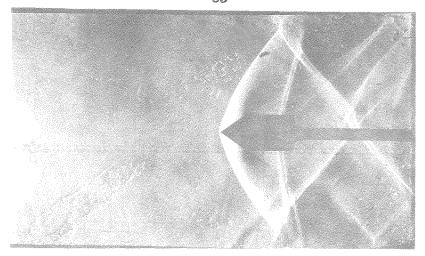


Fig. 28 M = 1.544 a = 00

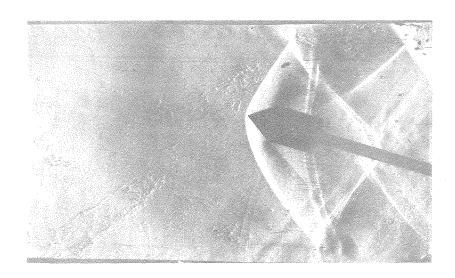


Fig. 29 M = 1.544 c = 15°

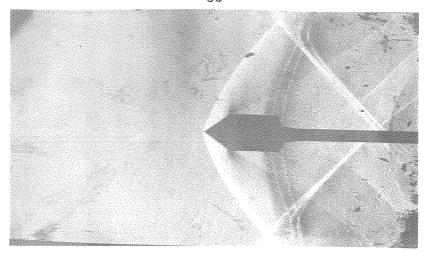


Fig. 30 M = 1.584 α = 0°

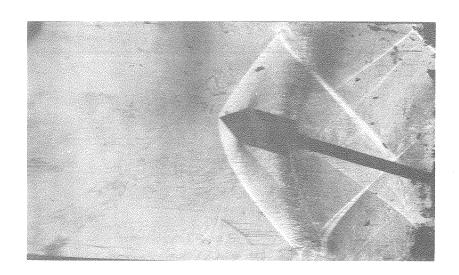


Fig. 31 M = 1.584 c = 150

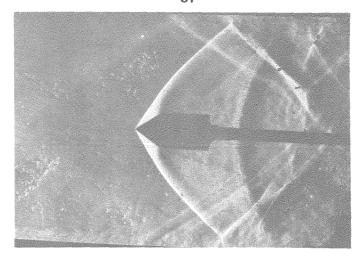


Fig. 32 M = 1.857 $c = 0^{\circ}$

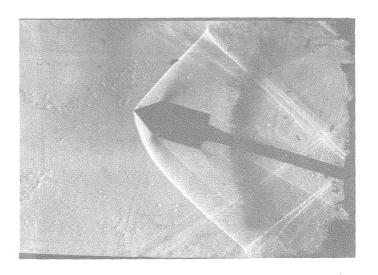


Fig. 33 M = 1.857 a = 15°